

Flows under a function

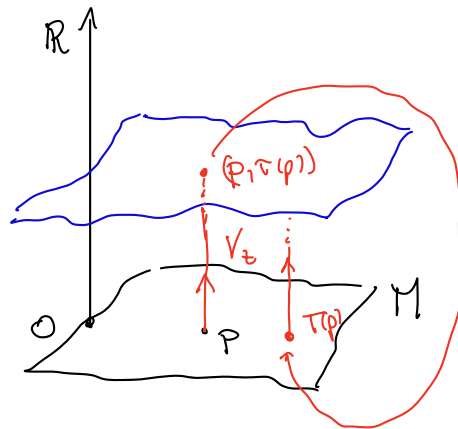
- M manifold, $T: M \rightarrow M$ base map, ν measure on M
 $\tau: M \rightarrow [0, +\infty)$, roof function, $\tau \in L^1(M, \nu)$

$$M_\tau = \{ (p, s) \in M \times \mathbb{R} \mid 0 \leq s \leq \tau(p) \} / \sim$$

with $(p, \tau(p)) \sim (T(p), 0)$

- $V = \{V_t\}$, flow under the function τ

$$M_\tau \ni (p, s) \mapsto V_t(p, s) = (p, s+t)$$



Thm Let Φ measure-preserving flow on a Lebesgue space with essentially no fixed points, then Φ is isomorphic to a flow under a function.

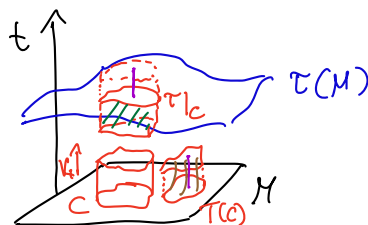
Prop Let (M, ν) be a measure space and $T: M \rightarrow M$ measure-preserving.

Let $\tau: M \rightarrow [0, +\infty)$ be measurable and $\tau \in L^1(M, \nu)$.

Then $V = \{V_t\}$ on M_τ preserves the probability measure

$$\mu_\tau := \frac{\nu \times \ell}{\int_M \tau d\nu}, \text{ where } \ell \text{ is the Lebesgue measure on } \mathbb{R}.$$

proof



$$A = C \times (s_1, s_2) \subset M \times \mathbb{R}$$

$$\nu(C) > 0, \mu_\tau(A) > 0$$

$$\mu_\tau(V_t(A)) = \mu_\tau(A) \quad \forall t \in \mathbb{R}.$$

$$\begin{aligned} \mu_\tau(V_t(A)) &= \mu_\tau(\underbrace{\{(p,s) / p \in C, t \leq s \leq \tau(p)\}}_{A = C \times (0, s_2)}) + \\ &\quad \mu_\tau(\underbrace{\{(T(p), s) / p \in C, 0 \leq s \leq s_2 + t - \tau(p)\}}) \\ &= \int_C (\tau(p) - t) d\nu + \int_{T(C)} (s_2 + t - \tau(T^{-1}(p))) d\nu = \int_C s_2 d\nu = \mu_\tau(A) \\ &\quad \int_C (s_2 + t - \tau(p)) d\nu \quad \square \end{aligned}$$

Prop $T: M \rightarrow M$ is ergodic w.r.t ν prob. meas.

$V = \{V_t\}$ is ergodic w.r.t $\mu_\tau = \frac{\nu \times \ell}{\int_M \tau d\nu}$

proof

If T is ergodic, let $f: M \rightarrow \mathbb{R}$ be V -invariant
($f \circ V_t = f$ for all t and μ_τ -e.e.). Then one can define

$$g: M \rightarrow \mathbb{R}, \quad g(p) = \frac{1}{\tau(p)} \int_0^{\tau(p)} f(p, s) ds, \quad \nu\text{-e.e.}$$

with $g(p) = f(p, 0)$, $g(T(p)) = f(T(p), 0)$.

But $f(T(p), 0) = f \circ V_t(p, 0)$ for $t = \tau(p)$, then $f(T(p), 0) = f(p, 0)$.

hence g is T -invariant $\Rightarrow g$ is ν -e.e. constant.

$\Rightarrow f$ is μ_τ -e.e. constant.

If V is ergodic on M_τ , let $g: M \rightarrow \mathbb{R}$ be T -invariant.

Then one can define $f(p, s) = g(p) \quad \forall p \in M, s \in [0, \tau(p)]$.

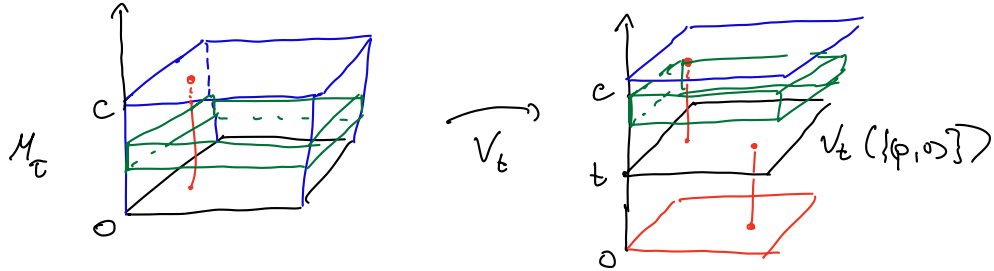
Then f is V -invariant $\Rightarrow f$ is μ_τ -e.e. constant

$\Rightarrow g$ is ν -e.e. constant. □

Remarks

- V ergodic $\Leftrightarrow V_t: M_\tau \rightarrow M_\tau$ is ergodic for all t up to a countable set.

Ex Let $\tau: M \rightarrow \mathbb{R}$, $\tau \equiv c > 0$, (M_τ, V) .



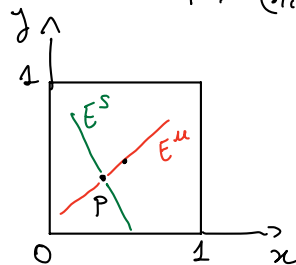
V_{cm} is not ergodic $\forall m \in \mathbb{Z}$.

- $M = \mathbb{A}^{\mathbb{Z}}$ with $\mathbb{A} = \{1, \dots, N\}$, $\sigma: \mathbb{A}^{\mathbb{Z}} \rightarrow \mathbb{A}^{\mathbb{Z}}$ shift

- $M = \mathbb{T}^2$, $T: M \rightarrow M$ hyperbolic automorphism

Ex $T =$ Arnold cat map.

$$T: (x, y) \mapsto \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \pmod{\mathbb{Z}^2}.$$



$$E^s = \text{Span}(v_s)$$

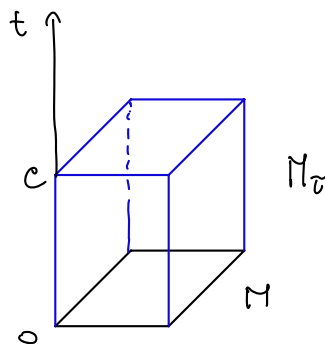
$$E^u = \text{Span}(v_u)$$

$$Av_s = \lambda_- v_s, \quad Av_u = \lambda_+ v_u$$

$$0 < \lambda_- < 1 < \lambda_+$$

$\tau: M \rightarrow (0, +\infty)$

$\tau \equiv c > 0$



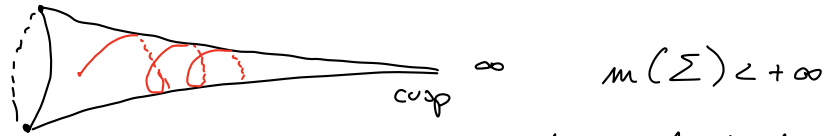
V on M_τ is Anosov, ergodic w.r.t $\mu_\tau := \frac{m \times l}{c}$

$$(p, s) \in M_\tau, \quad T_{(p, s)} M_\tau = E^c \oplus E^u \oplus E^s$$

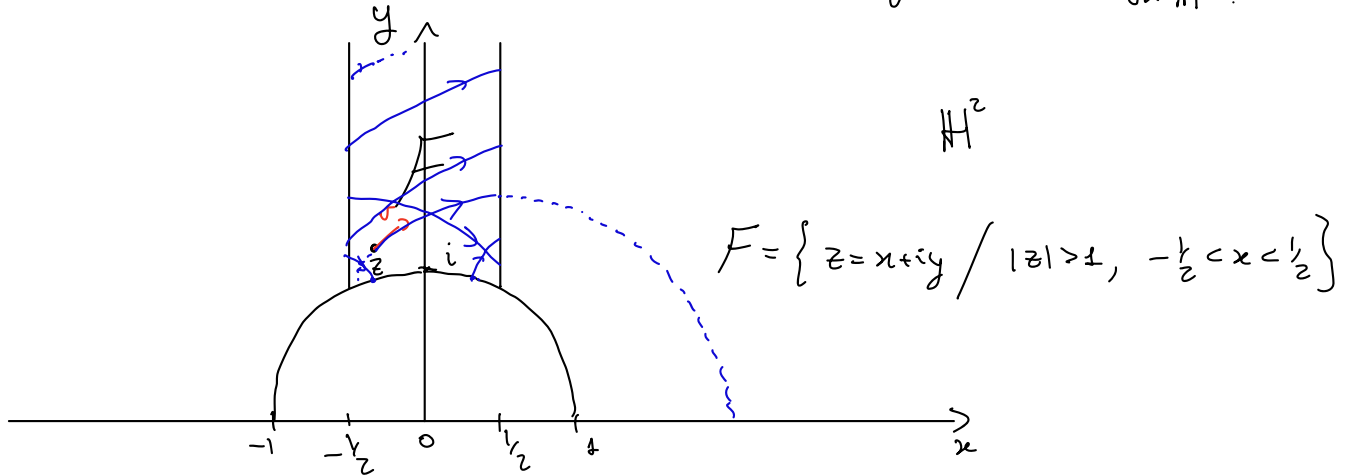
$$E^c = \text{Span}(0, 1)$$

Example \mathbb{H}^2 , $\Gamma = SL(2, \mathbb{Z}) < SL(2, \mathbb{R})$ is a lattice

$\Gamma \backslash \mathbb{H}^2 = \Sigma$ is called the modular surface, is an orbifold which has a smooth Riemannian surface with two singular points with finite volume (connected, orientable).



$$dm = \frac{1}{y^2} dx dy \quad \text{volume form on } \mathbb{H}^2.$$



$$\pi: \mathbb{H}^2 \rightarrow \Sigma = \Gamma \backslash \mathbb{H}^2,$$

$$z \in F, \\ v \in T_z \mathbb{H}^2 \\ |v| = 1$$

$$\varphi_t(z, v) = (\gamma_{(z,v)}(t), \gamma'_{(z,v)}(t)) \in T^1 \mathbb{H}^2$$

$$\tilde{\varphi}_t: T^1 \Sigma \rightarrow T^1 \Sigma, \quad \tilde{\varphi}_t(z, v) = d\pi(\varphi_t(z, v))$$



$$C := \{ (z, v) \in T^1 \Sigma \mid z \in F, \operatorname{Re}(z) = 0, \mathcal{I}(v) \neq 0, \pi \}$$

is a good Poincaré section for $\{\tilde{\varphi}_t\}$ geodesic flow on $T^1 \Sigma$.

$$I_+ = \{ z \in \mathbb{H}^2 \mid z = x + iy, x = 0, y > 1 \}, \quad I_- = \{ z = x + iy \mid x = 0, 0 < y < 1 \}$$

$$S = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \in SL(2, \mathbb{Z}), \quad \psi_S(I_+) = I_-, \quad \psi_S(I_-) = I_+$$

$$\psi_S(z) = -\frac{1}{z}, \quad z = iy, \quad \psi_S(iy) = \frac{i}{y}$$

$$d\psi_S(z, v) = (\psi_S(z), d_z \psi_S(v)) = (\psi_S(z), \psi'_S(z)v)$$

$$\psi'_S(z) = \frac{1}{(z+i)^2} = \frac{1}{z^2}$$

$$d\psi_S(iy, v) = \left(\frac{i}{y}, -\frac{1}{y^2}v \right) = (z', v') \quad \mathcal{I}(v') = \mathcal{I}(v) + \pi \pmod{2\pi}$$

$$\mathcal{C} := d\pi \left(\left\{ (z, v) \in T^*\mathbb{H}^2 / z \in \mathbb{I}_+ \cup \mathbb{I}_- \cup \{i\}, \vartheta(v) \in (-\pi, 0) \right\} \right)$$

