

Thm If  $\Gamma < SL(2, \mathbb{R})$  is a lattice (discrete subgroup s.t.  $\Sigma = \Gamma \backslash \mathbb{H}^2$  is of finite volume) then the action of non-elliptic element  $g \in SL(2, \mathbb{R})$  on  $T^1(\Gamma \backslash \mathbb{H}^2)$  is ergodic.

Proof

$$SL(2, \mathbb{R}) \ni h \mapsto \rho(h) = \langle f \circ h, f \rangle_{L^2}, \quad f \in L^2(T^1\Sigma).$$

$\rho$  is continuous and if  $f$  is  $\tau_b$ -invariant ( $\tau_b = \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix}$ ) then  $\rho(\tau_b^m h \tau_b^{-m}) = \rho(h)$ .

Let  $\{\varepsilon_k\} \searrow 0$  s.t.  $b\varepsilon_k \in \mathbb{R} \setminus \mathbb{Q}$  and it's possible to find sequences  $\{m_k\}, \{n_k\} \subset \mathbb{Z}$  s.t.

$$|b\varepsilon_k m_k - 1| < \varepsilon_k$$

$$\left| m_k b \varepsilon_k + \frac{m_k b \varepsilon_k}{m_k b \varepsilon_k + 1} \right| < \varepsilon_k.$$

$$h_k = \exp(\varepsilon_k H_-) = \begin{pmatrix} 1 & 0 \\ \varepsilon_k & 1 \end{pmatrix} \xrightarrow{k \rightarrow +\infty} \text{Id}$$

$$\tau_b^{m_k} h_k \tau_b^{-n_k} = \begin{pmatrix} 1 + m_k b \varepsilon_k & (1 + m_k b \varepsilon_k) m_k b + m_k b \\ \varepsilon_k & 1 + m_k b \varepsilon_k \end{pmatrix} \xrightarrow{k \rightarrow +\infty} \begin{pmatrix} 2 & r \\ 0 & \frac{1}{2} \end{pmatrix} \quad \begin{matrix} \uparrow \\ \bar{h} \end{matrix}$$

$\bar{h}$  is a hyperbolic element, then  $\bar{h} \sim \lambda_a$  for some  $a \in \mathbb{R} \setminus \{\pm 1, 0\}$ .

$$\left. \begin{array}{l} \rho(\tau_b^{m_k} h_k \tau_b^{-n_k}) = \rho(h_k) \xrightarrow{k \rightarrow +\infty} \rho(\text{Id}) = \|f\|_{L^2}^2 \\ \downarrow k \rightarrow +\infty \\ \rho(\bar{h}) \end{array} \right\} \Rightarrow \rho(\bar{h}) = \|f\|_{L^2}^2$$

$\Rightarrow f$  is  $\bar{h}$ -invariant.  $\Rightarrow f$  is constant  $\mu$ -a.e. □

Remarks  $f$  is  $\lambda_a$ -invariant and  $\rho(\lambda_a^m h \lambda_a^{-m}) = \rho(h) \quad \forall m, m \in \mathbb{Z}$   
and

$$\lambda_a^m \tau_b \lambda_a^{-m} \xrightarrow{m \rightarrow -\infty} \text{Id}, \quad a > 1$$

$$\begin{pmatrix} a^m & 0 \\ 0 & a^{-m} \end{pmatrix} \begin{pmatrix} 1 & b \\ 0 & 1 \end{pmatrix} \begin{pmatrix} a^{-m} & 0 \\ 0 & a^m \end{pmatrix} = \begin{pmatrix} 1 & b a^{2m} \\ 0 & 1 \end{pmatrix} = \tau_{b a^{2m}}$$

Prop Let  $\Phi = \{\varphi_t\}$  be the geodesic flow on  $\mathbb{H}^2$ , and  $\{u_s^\pm\}$  the positive (negative) horocycle flow.

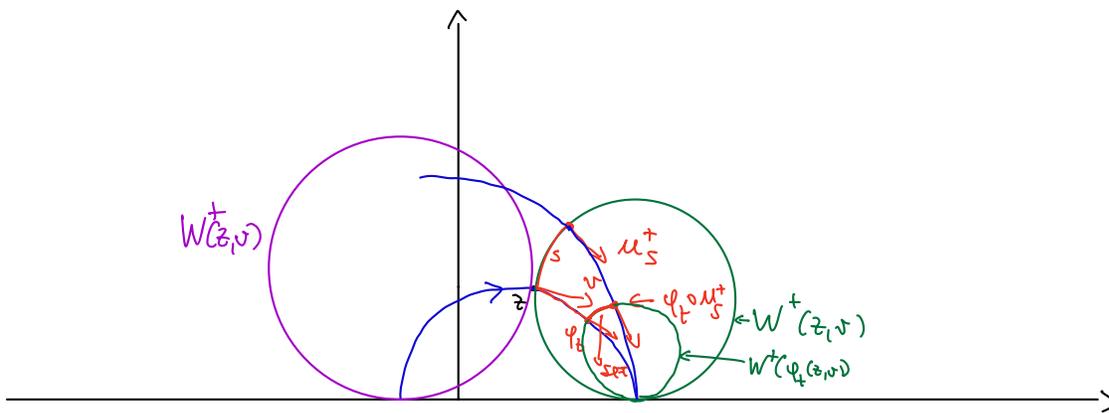
In  $\text{PSL}(2, \mathbb{R})$   $\varphi_t$  is given by the right action of  $z \mapsto z + t$

$$u_s^\pm \quad u \quad u \quad u \quad u \quad u \quad u \quad \gamma_s \text{ exp}(sH)$$

Then  $\forall t, s \in \mathbb{R}$

$$\varphi_t \circ u_s^\pm = u_{se^\pm t}^\pm \circ \varphi_t$$

$$\left[ \varphi_{-t} \circ u_s^+ \circ \varphi_t = u_{se^t}^+ \xrightarrow{t \rightarrow -\infty} \text{Id} \right]$$



Corollary The geodesic and horocycle flows on  $\Sigma = \Gamma \backslash \mathbb{H}^2$  with  $\Gamma < \text{SL}(2, \mathbb{R})$  a lattice, are ergodic with respect to the Liouville measure  $\mu = m \times l$ .

← →

Non-constant curvature case.

Thm (Hopf) Let  $\Sigma$  be a smooth closed connected orientable Riemannian surface with negative curvature. Then, the geodesic flow  $\Phi = \{\varphi_t\}$  on  $\Sigma$  is ergodic w.r.t the Liouville measure  $\mu = m \times l$ .

proof The Liouville measure  $\mu$  is finite and  $\Phi$ -invariant.  $\mu \sim \alpha \wedge \beta$   
 If  $g : T^1\Sigma \rightarrow \mathbb{C}$ ,  $g \in L^1(T^1\Sigma, \mu)$ ,  $\exists g_\Phi > 0$ .

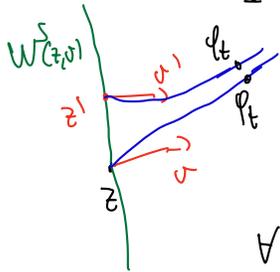
$$g_{\Phi}(z, v) = \lim_{T \rightarrow +\infty} \frac{1}{|T|} \int_0^{|T|} g(\varphi_t(z, v)) dt \text{ for } \mu\text{-a.e. } (z, v).$$

Let  $f \in L^1(T^1\Sigma, \mu)$  and assume that  $f$  is  $\Phi$ -invariant. Wlog  $f > 0$ ,  $\forall C > 0$ , let  $f_C := \min\{f, C\}$ .  $f_C \in L^1$ , bounded then  $\exists \{g_m\} \subset C^0(T^1\Sigma)$  s.t.  $\|f_C - g_m\|_{L^1} \xrightarrow{m \rightarrow +\infty} 0$ .

Then let  $(z, v) \in T^1\Sigma$  and  $W^s(z, v)$  be the strong stable manifold.

Then,  $\forall m \exists N_m^s \subset W^s(z, v)$  s.t.  $\forall (z', v') \in W^s(z, v) \setminus N_m^s$   
 $\mu(N_m^s) = 0$

$$\int_{(g_m)_{\Phi}}(z', v') = \lim_{T \rightarrow +\infty} \frac{1}{T} \int_0^T g_m(\varphi_t(z', v'))$$



$$\text{Then } (g_m)_{\Phi}(z', v') = (g_m)_{\Phi}(z, v)$$

$$\forall \varepsilon > 0 \exists T_{\varepsilon} \text{ s.t. } d(\varphi_t(z, v), \varphi_t(z', v')) < \varepsilon \quad \forall t > T_{\varepsilon}$$

$$\text{Then } \forall \gamma > 0 \exists T_{\gamma} \text{ s.t. } |g_m(\varphi_t(z, v)) - g_m(\varphi_t(z', v'))| < \gamma \quad \forall t > T_{\gamma}$$

$$\Rightarrow |(g_m)_{\Phi}(z, v) - (g_m)_{\Phi}(z', v')| < \gamma.$$

$$\text{Then } \|f - g_m\|_{L^1} \geq \int_{T^1\Sigma} |f(z, v) - g_m(z, v)| d\mu = \int_{T^1\Sigma} |f(\varphi_t(z, v)) - g_m(\varphi_t(z, v))| d\mu$$

$f$  is  $\Phi$ -invariant

$$\downarrow = \int_{T^1\Sigma} |f(z, v) - g_m(\varphi_t(z, v))| d\mu$$

$\mu$  is  $\Phi$ -invariant

$$\Rightarrow \int_{T^1\Sigma} |f(z, v) - \frac{1}{T} \int_0^T g_m(\varphi_t(z, v)) dt| d\mu \leq \frac{1}{T} \int_0^T \left( \int_{T^1\Sigma} |f(z, v) - g_m(\varphi_t(z, v))| d\mu \right) dt$$

$$\leq \frac{1}{T} \int_0^T \|f - g_m\|_{L^1} dt$$

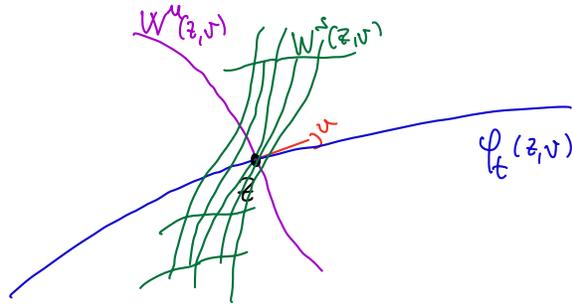
$$\leq \|f - g_m\|_{L^1}$$

$$\Rightarrow \lim_{m \rightarrow +\infty} \|f - (g_m)_{\Phi}\|_{L^1} = 0.$$

Then  $\exists \mathcal{N}^s := \bigcup_m \mathcal{N}_m^s$ ,  $\mu(\mathcal{N}^s) = 0$ , s.t.  $\forall (z', v') \in W^s(z, v) \setminus \mathcal{N}^s$   
 $f(z', v') = \lim_{m \rightarrow \infty} (g_m)_{\Phi}(z', v') = \lim_{m \rightarrow \infty} (g_m)_{\Phi}(z, v) = f(z, v)$

Then  $f$   $\Phi$ -invariant  $\Rightarrow \exists \mathcal{N}^s, \mathcal{N}^u$ ,  $\mu(\mathcal{N}^s) = \mu(\mathcal{N}^u) = 0$  s.t.

$$f(z', v') = f(z, v) \quad \forall (z', v') \in (W^s(z, v) \setminus \mathcal{N}^s) \cup (W^u(z, v) \setminus \mathcal{N}^u)$$



$$W^{cs}(z, v) = \bigcup_{t \in \mathbb{R}} \varphi_t(W^s(z, v))$$

Let  $(z, v) \in T^2\Sigma$ ,  $U$  be an open set s.t.  $U \cap W^{cs}(z, v) = \bigcup_{t \in (T, T)} W_{loc}^s(\varphi_t(z, v))$

Then  $\exists$  a measurable family of positive function  $h_z: W_{loc}^s(\varphi_t(z, v)) \rightarrow \mathbb{R}$  s.t.

$\forall A \subset U$  measurable

$$\mu_{cs}(A \cap W^{cs}(z, v)) = \int_{-T}^T \left( \int_{W_{loc}^s(\varphi_t(z, v))} h_z(z', v') \chi_A(z', v') d\mu_s(z', v') \right) dt$$

$\mu|_{W^{cs}(z, v)}$    $\mu|_{W_{loc}^s}$

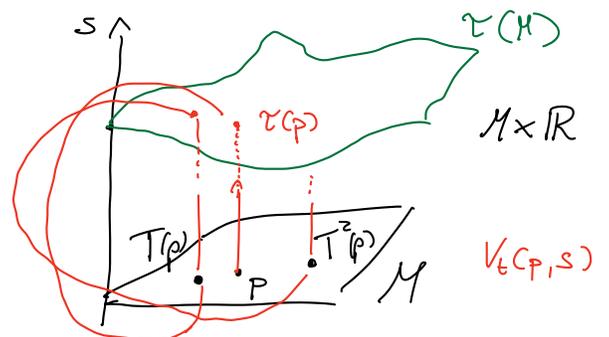
Then  $f$   $\Phi$ -invariant  $\Rightarrow f$  is constant  $\mu$ -e.e. □



### Flows under a function

$T: M \rightarrow M$ ,  $M$  manifold

$\tau: M \rightarrow [0, +\infty)$



Def Given a manifold  $M$ , a map  $T$ , and a function  $\tau: M \rightarrow [0, +\infty)$ ,  
 let  $M_\tau := \{ (p, s) \mid p \in M, 0 \leq s \leq \tau(p) \} / \sim$

with  $(p, \tau(p)) \sim (T(p), 0)$ . The function  $\tau$  is called the roof function, the map  $T$  is called the base map.

Then we define the semi-flow  $V_t: M_\tau \rightarrow M_\tau$  given by

$$(p, s) \mapsto V_t(p, s) = (p, s+t) \quad \forall t \geq 0.$$

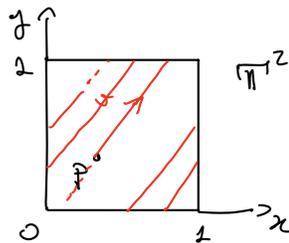
If  $T$  is invertible then  $\{V_t\}$  is a flow.

$\{V_t\}$  is called the flow on  $M$  under the function  $\tau$ . (special flows, suspension flows)

Warning Suspension flows is sometimes used for flows under a constant function.

Ex Poincaré section and map.

$\{\varphi_t\}$  on  $\mathbb{T}^2$ ,  $p \mapsto p + t v$ , for  $v \in \mathbb{R}^2$  fixed.



If  $v = (v_1, v_2)$  has  $v_2 \neq 0$  then  $M = \{y=0\}$  is a Poincaré section

Then the Poincaré map  $T: M \rightarrow M$ ,  $(x, 0) \mapsto \varphi_{t(x,0)}(x, 0)$  where

$$t(x, 0) = \min \{ t > 0 \mid \varphi_t(x, 0) \in M \} = \frac{x}{v_2}$$

$$S^1 = M \ni (x, 0) \mapsto T(x, 0) = \left( x + \frac{v_1}{v_2}, 0 \right) \in M$$

