

$$(z, v) \in T^1 \mathbb{H}^2 \cong PSL(z, \mathbb{R}) = SL(z, \mathbb{R}) / \pm I$$

$$z = x + iy, \quad v = i y (\cos \theta + i \sin \theta)$$

$$SL(z, \mathbb{R}) \ni g_{(z, v)} = \begin{pmatrix} \sqrt{y} & x\sqrt{y} \\ 0 & \sqrt{y} \end{pmatrix} \begin{pmatrix} \cos \theta/2 & \sin \theta/2 \\ -\sin \theta/2 & \cos \theta/2 \end{pmatrix}$$

$$(z, v) = d \psi_{g_{(z, v)}}(i, i)$$

Prop The geodesic flow on \mathbb{H}^2 is conjugate to the right action of $\{\lambda_a\}_{a>0}$ on $SL(z, \mathbb{R})$.

$$g_{(z, v)} \hookrightarrow (z, v) \quad \text{Then} \quad \varphi_t(z, v) \hookrightarrow g_{\varphi_t(z, v)} = g_{(z, v)} \begin{pmatrix} e^{tr_2} & 0 \\ 0 & e^{-tr_2} \end{pmatrix}$$

$$\underline{\text{Proof}} \quad (i, i) \hookrightarrow g_{(i, i)} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\varphi_t(i, i) = (i e^t, i e^t), \quad g_{\varphi_t(i, i)} = \begin{pmatrix} e^{tr_2} & 0 \\ 0 & e^{-tr_2} \end{pmatrix}$$

$$(z, v) \hookrightarrow g_{(z, v)} \Leftrightarrow (z, v) = d \psi_{g_{(z, v)}}(i, i)$$

$$\varphi_t(z, v) \quad d \psi_{g_{(z, v)}}(i e^t, i e^t) = \varphi_t(z, v)$$

$$g_{\varphi_t(z, v)} = g_{(z, v)} g_{(i e^t, i e^t)} = g_{(z, v)} \begin{pmatrix} e^{tr_2} & 0 \\ 0 & e^{-tr_2} \end{pmatrix} \quad \square$$

$$\underline{\text{Remark}} \quad \gamma_{(z, v)}(t), \quad \gamma_{(z, v)}^\pm := \lim_{t \rightarrow \pm\infty} \gamma_{(z, v)}(t)$$

$$g_{(z, v)} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in SL(z, \mathbb{R}), \quad \gamma_{(z, v)}^\pm = \lim_{t \rightarrow \pm\infty} \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} e^{tr_2} & 0 \\ 0 & e^{-tr_2} \end{pmatrix} i =$$

$$= \lim_{t \rightarrow \pm\infty} \begin{pmatrix} a e^{t/2} & b e^{-t/2} \\ c e^{t/2} & d e^{-t/2} \end{pmatrix} i = \lim_{t \rightarrow \pm\infty} \frac{a e^{t/2} i + b e^{-t/2}}{c e^{t/2} i + d e^{-t/2}}$$

$$\gamma_{(z,v)}^+ = \frac{a}{c}, \quad \gamma_{(z,v)}^- = \frac{b}{d}, \quad \left(\frac{1}{0} = \infty\right)$$

$$T_{(z,v)}(T^*H^2) \cong \mathfrak{sl}(2, \mathbb{R}) := \{ A \in M(2 \times 2, \mathbb{R}) / \text{tr } A = 0 \} \quad V(z,v)$$

$$\dim \mathfrak{sl}(2, \mathbb{R}) = 3, \quad \text{basis } X = \begin{pmatrix} 1/2 & 0 \\ 0 & -1/2 \end{pmatrix}, \quad H_+ = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \quad H_- = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

A perturbation of (z,v) is of the form (z',v') s.t. $g_{(z',v')} = g_{(z,v)} \exp(\delta A)$

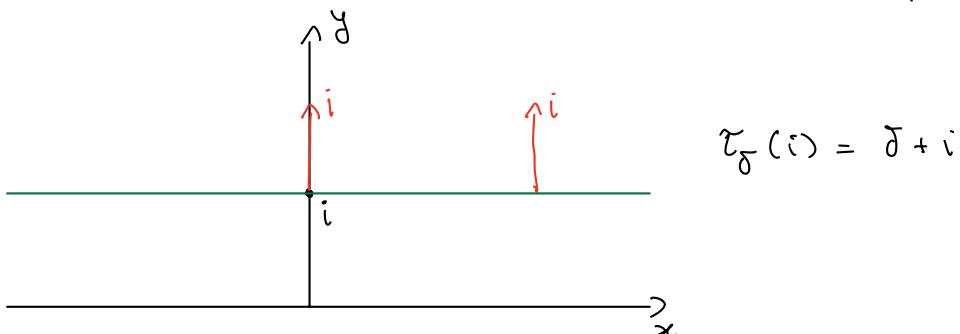
$$A \in \{X, H_+, H_-\}$$

- $g_{(z',v')} = g_{(z,v)} \exp(\delta X), \text{ for small } \delta.$

$$\begin{pmatrix} e^{\delta/2} & 0 \\ 0 & e^{-\delta/2} \end{pmatrix} \quad X = \text{vector field of the geodesic flow.}$$

- $g_{(z',v')} = g_{(z,v)} \exp(\delta H_+) = g_{(z,v)} \tau_\delta = g_{(z,v)} \begin{pmatrix} 1 & \delta \\ 0 & 1 \end{pmatrix}$

$$(z,v) = (i,i), \quad W^+(i,i) := \left\{ (z',v') / g_{(z',v')} = \underbrace{g_{(i,i)} \begin{pmatrix} 1 & \delta \\ 0 & 1 \end{pmatrix}}_{\begin{pmatrix} 1 & \delta \\ 0 & 1 \end{pmatrix}} \right\}_{\delta \in \mathbb{R}}$$



$$W^+(i,i) = \{(x+i, i) / x \in \mathbb{R}\} \subset T^*H^2.$$

- $W^-(i,i) := \{(z',v') / g_{(z',v')} = g_{(i,i)} \exp(\delta H_-) = \begin{pmatrix} 1 & 0 \\ \delta & 1 \end{pmatrix}\}_{\delta \in \mathbb{R}}$

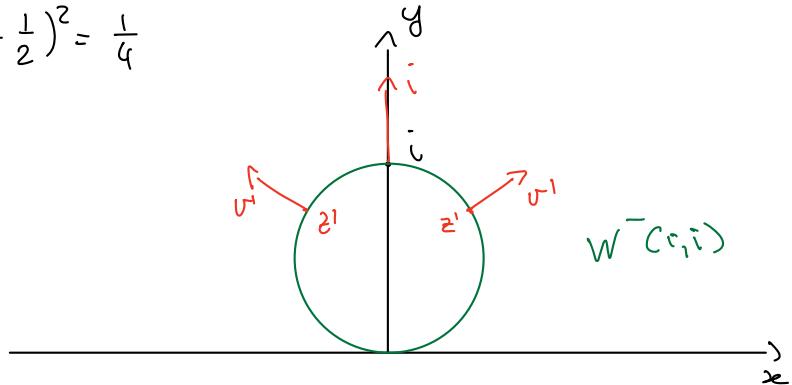
$$H_- = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \quad \exp(\delta H_-) = \begin{pmatrix} 1 & 0 \\ \delta & 1 \end{pmatrix}$$

$$(z^1, v^1) = (x^1 + iy^1, iy^1(\cos \vartheta^1 + i \sin \vartheta^1))$$

$$x^1 + iy^1 = \begin{pmatrix} 1 & 0 \\ \delta & 1 \end{pmatrix} i = \frac{i}{\delta i + 1} = \frac{i(1 - \delta i)}{1 + \delta^2} = \underbrace{\frac{\delta}{1 + \delta^2}}_{x^1} + \underbrace{\frac{1}{1 + \delta^2} i}_{y^1}$$

$$\vartheta^1 = -2 \operatorname{arctan} \frac{c}{d} = -2 \operatorname{arctan} \delta = -2 \operatorname{arctan} \frac{x^1}{y^1}.$$

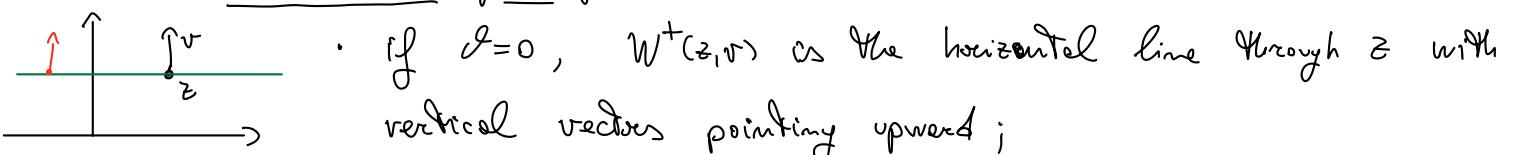
$$(x^1)^2 + (y^1 - \frac{1}{2})^2 = \frac{1}{4}$$



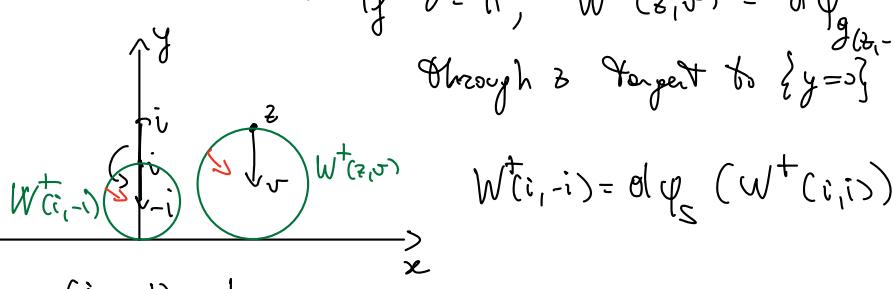
- For $(z, v) \in T^1 \mathbb{H}^2$, $W^\pm(z, v) = d\psi_{g_{(z, v)}}(W^\pm(i, i))$

Def Given $(z, v) \in T^1 \mathbb{H}^2$ and $\gamma_{(z, v)}(t)$ the geodesic for (z, v) , we call:

- Positive Horocycle of (z, v) the set $W^+(z, v)$, which is



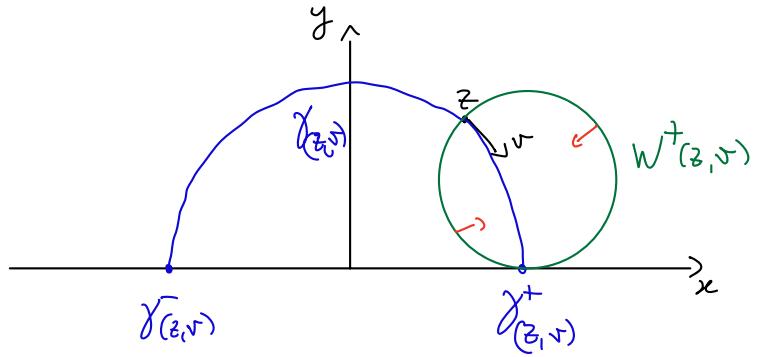
- if $\vartheta = \pi$, $W^+(z, v) = d\psi_g(z, v) \circ d\psi_s(W^+(i, i))$ is the circle through z tangent to $\{y=0\}$ at $x = \operatorname{Re}(z) = \gamma_{(z, v)}^+$, with vectors pointing inside.



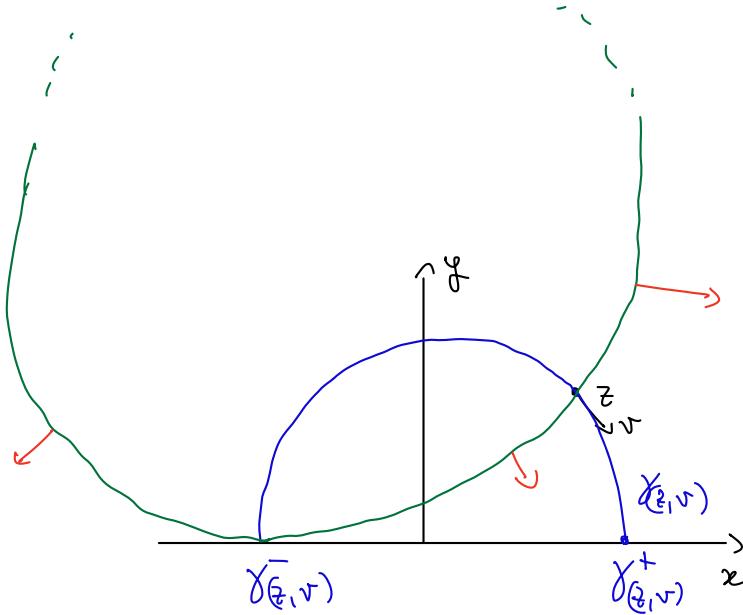
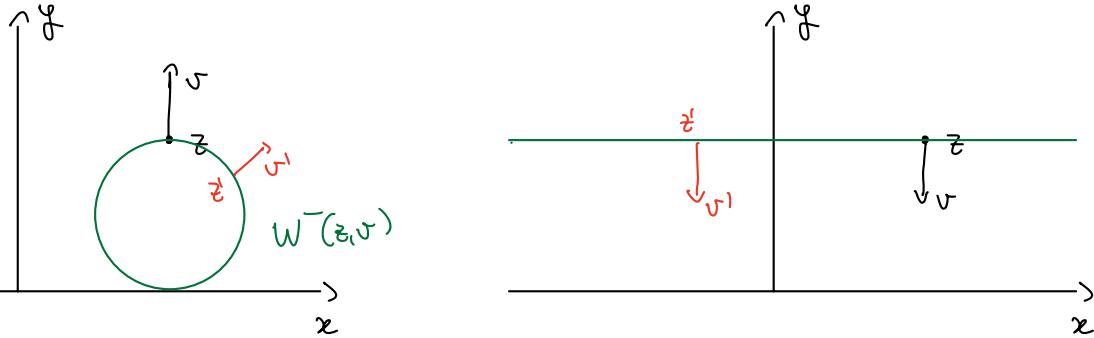
$$(i, -i) = d\psi_s(i, i)$$

$$S = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

- if $\vartheta \neq 0, \pm \pi$, $W^+(z, v)$ is the circle through z tangent to $\{y=0\}$ at $\gamma_{(z, v)}^+$, with vectors pointing inside.



- Negative Holonomy for (z, v) is $W^-(z, v)$



Def We consider the distance d_h on $T^1\mathbb{H}^2$ given by

$$d_h((z, v), (z', v')) = \sqrt{d_{\mathbb{H}^2}(z, z')^2 + (\hat{v}v')^2} \quad \forall (z, v), (z', v') \in T^1\mathbb{H}^2$$

[$v \in T_z\mathbb{H}^2$, $v' \in T_{z'}\mathbb{H}^2$, then $\hat{v}v'$ is the angle between v' and the vector \hat{v} obtained by parallel transport from z to z' , i.e.

Let γ be the geodesic ray z and z' , $z = \gamma(t_0)$, $z' = \gamma(t_1)$, then

$$\bar{v} = d_z(\pi \circ \varphi_{(t_1-t_0)})(v)]$$

Prop Let $(x+i, i) \in W^+(i, i)$, then

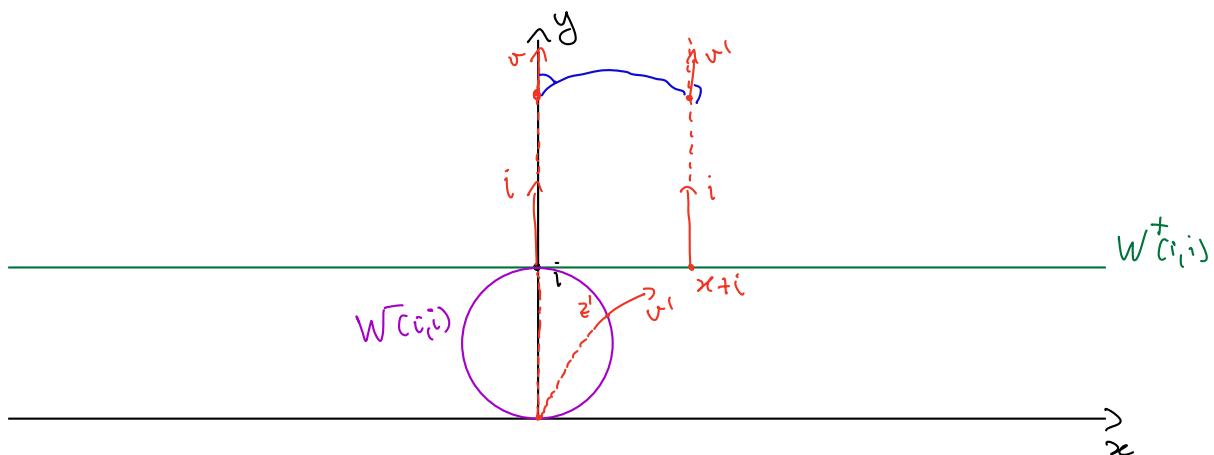
$$\lim_{t \rightarrow +\infty} e^t d_h(\varphi_t(i, i), \varphi_t(x+i, i)) = \sqrt{2} |x|.$$

$$d_h \sim e^{-t} \cdot \sqrt{2} |x|$$

Let $(z', v') \in W^-(i, i)$, then

$$\lim_{t \rightarrow -\infty} e^{-t} d_h(\varphi_t(i, i), \varphi_t(z', v')) = \sqrt{2} \left| \frac{\operatorname{Re}(z')}{\operatorname{Im}(z')} \right|$$

$$d_h \sim e^t \cdot \sqrt{2} \left| \frac{\operatorname{Re}(z')}{\operatorname{Im}(z')} \right|$$



Proof

$$\cdot \underline{W^+(i, i)} \quad \varphi_t(i, i) = (ie^t, ie^t), \quad \varphi_t(x+i, i) = (x+ie^t, ie^t)$$

$$d(i e^t, x+ie^t) \sim e^{-t} |x| \sim v' v \quad \text{as } t \rightarrow +\infty$$

$$\begin{aligned} \cdot \underline{W^-(i, i)} \quad & d_h(\varphi_t(i, i), \varphi_t(z, v)) = d_h(\varphi_{-t}(i, -i), \varphi_{-t}(z, -v)) = \\ & (z, -v) \in W^+(i, -i) = d_{\psi_s}(W^+(i, i)) \\ & = d_h(\underbrace{d_{\psi_s}(\varphi_{-t}(i, -i)), d_{\psi_s}(\varphi_{-t}(z, -v))}_{\varphi_{-t}(i, i)}) = d_h(\varphi_{-t}(i, i), \underbrace{d_{\psi_s}(\varphi_{-t}(z, -v))}_{W^+(i, i)}) \end{aligned}$$

$$\lim_{t \rightarrow -\infty} e^{-t} d_h(\varphi_t(i, i), \varphi_t(z, v)) = \lim_{t \rightarrow -\infty} e^{-t} d_h(\varphi_{-t}(i, i), d_{\psi_s}(\varphi_{-t}(z, -v)))$$

$$= \lim_{t \rightarrow +\infty} e^t d_h(\varphi_t(i, i), d_{\psi_s}(\varphi_t(z, v))) = \sqrt{2} |\tilde{x}| = \sqrt{2} \left| \frac{\operatorname{Re}(z)}{\operatorname{Im}(z)} \right|$$

$$d\psi_S(\varphi_t(z, v)) = (\tilde{x} + ie^t, ie^t)$$

$$(z, v) \in W^-(z, v) \Rightarrow x^2 + (y - \frac{1}{2})^2 = \frac{1}{4} \Leftrightarrow x^2 + y^2 = y$$

$\tilde{z} = x + iy$

$$d\psi_S(\varphi_t(z, v)) = (\tilde{x} + ie^t, ie^t) \text{ with } \tilde{x} + i = S z = -\frac{1}{z} = -\frac{x - iy}{x^2 + y^2} = -\frac{x}{y} + i$$

□

Prop $\forall (z, v) \in T^* \mathbb{H}^2$, the $T_{(z, v)}(T^* \mathbb{H}^2)$ can be written as the sum of three one-dimensional spaces

$$T_{(z, v)}(T^* \mathbb{H}^2) = E^c \oplus E^s \oplus E^u$$

where:

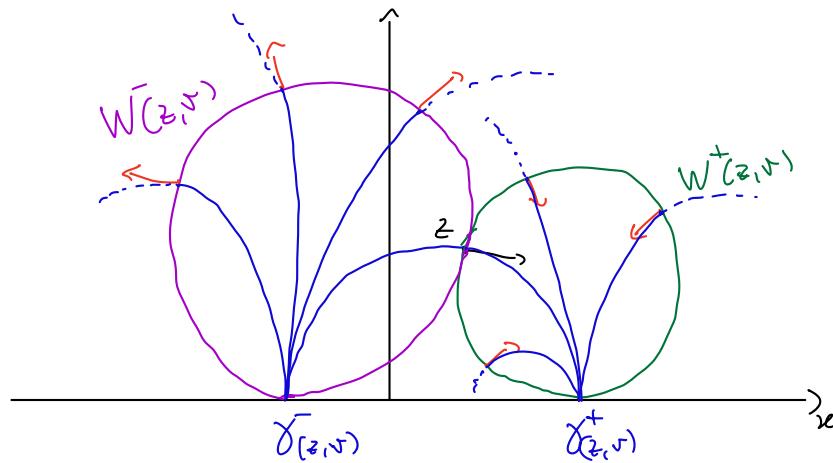
$$- E^c = \text{Span } X, \quad E^s = \text{Span}(H_+), \quad E^u = \text{Span}(H_-)$$

And if we move (z, v) along E^s we obtain (z', v') for which

$$\partial_h(\varphi_t(z, v), \varphi_t(z', v')) \sim e^{-t} \cdot \text{const}(z, z') \text{ as } t \rightarrow -\infty$$

$$\text{“ “ “ } \leftarrow E^u \text{ “ “ “ }$$

$$\partial_h(\varphi_t(z, v), \varphi_t(z, v)) \sim e^t \text{ const}(z, z) \text{ as } t \rightarrow \infty.$$



Def Given $(z, v) \in T^* \mathbb{H}^2$, the positive horocycle flow $\{\mu_s^+(z, v)\}_{s \in \mathbb{R}}$ slides (z, v) along $W^+(z, v)$, and

$$d\mu_s^+(z, v) = d_{(z, v)} \underbrace{\begin{pmatrix} 1 & s \\ 0 & 1 \end{pmatrix}}_{\exp(sH_+)}$$

Given $(z, v) \in T^1 \mathbb{H}^2$, the negative horocycle flow $\{u_s^-(z, v)\}_{s \in \mathbb{R}}$ slides (z, v) along $W^-(z, v)$, and

$$d_{u_s^-(z, v)} = d_{(z, v)} \underbrace{\begin{pmatrix} 1 & 0 \\ s & 1 \end{pmatrix}}_{\exp(SH_-)}$$