

# Esercizi su Affinità

4.13  $f, g$  rotaz. di  $\pi/2$  intorno a 2 punti del piano - Mostrare che  $f \circ g$  è una riflessione intorno a un punto  $R$

$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x - x_p \\ y - y_p \end{pmatrix} + \begin{pmatrix} x_p \\ y_p \end{pmatrix} = \begin{pmatrix} -y + y_p + x_p \\ x - x_p + y_p \end{pmatrix}$$

$$g \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x - x_q \\ y - y_q \end{pmatrix} + \begin{pmatrix} x_q \\ y_q \end{pmatrix} = \begin{pmatrix} -y + y_q + x_q \\ x - x_q + y_q \end{pmatrix}$$

$$(f \circ g) \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -x + x_q - y_q + y_p + x_p \\ -y + y_q + x_q - x_p + y_p \end{pmatrix} =$$

$$\begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} x_p + x_q + y_p - y_q \\ -x_p + x_q + y_p + y_q \end{pmatrix}$$

$$\frac{x_A + x_{A'}}{2} = x_R$$

$$\frac{y_A + y_{A'}}{2} = y_R$$

$$x_{A'} = 2x_R - x_A$$

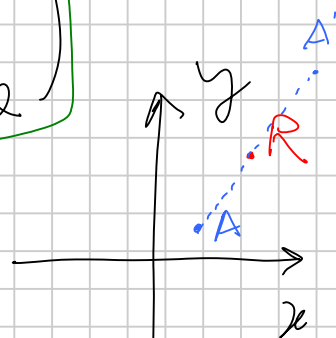
$$y_{A'} = 2y_R - y_A$$

$$S_R \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} 2x_R \\ 2y_R \end{pmatrix}$$

$$x_R = \frac{x_p + x_q + y_p - y_q}{2}$$

$$y_R = \frac{-x_p + x_q + y_p + y_q}{2}$$

In questo modo, abbiamo anche determinato  $R$



$$R_p = \begin{pmatrix} 0 & -1 & x_p + y_p \\ 1 & 0 & -x_p + y_p \\ 0 & 0 & 1 \end{pmatrix}$$

$$R_q = \begin{pmatrix} 0 & -1 & x_q + y_q \\ 1 & 0 & -x_q + y_q \\ 0 & 0 & 1 \end{pmatrix}$$

$f \circ g$  ha come matrice associata  $R_p \cdot R_q$

$$\begin{pmatrix} 0 & -1 & x_p + y_p \\ 1 & 0 & -x_p + y_p \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & -1 & x_q + y_q \\ 1 & 0 & -x_q + y_q \\ 0 & 0 & 1 \end{pmatrix} =$$

$$\begin{pmatrix} -1 & 0 & x_q - y_q + x_p + y_p \\ 0 & -1 & x_q + y_q - x_p + y_p \\ 0 & 0 & 1 \end{pmatrix}$$

$$g \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} x_q + y_q \\ -x_q + y_q \end{pmatrix}$$

$$f \begin{pmatrix} x \\ y \end{pmatrix} = A \begin{pmatrix} x \\ y \end{pmatrix} + b \quad \begin{pmatrix} A & | & b \\ \hline 0 & \dots & 0 & | & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ 1 \end{pmatrix}$$

$$4.15 \quad f(x) = Ax + b \quad r_1 \quad r_2 \quad r_3$$

$$f(r_1) = r_2$$

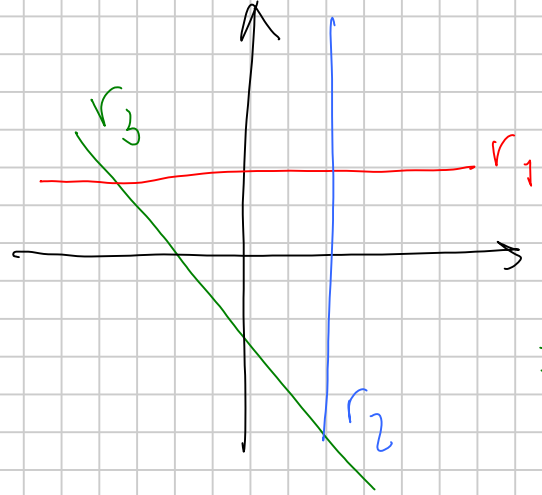
$$f(r_2) = r_3$$

$$f(r_3) = r_1$$

$$r_1: y=1$$

$$r_2: x=1$$

$$r_3: x+y=-1$$



$$r_1: \begin{cases} x=t \\ y=1 \end{cases} \quad r_2: \begin{cases} x=1 \\ y=u \end{cases} \quad \begin{matrix} t \in \mathbb{R} \\ u \in \mathbb{R} \end{matrix}$$

$\forall t \in \mathbb{R} \exists u$  tale che

$$* f \begin{pmatrix} t \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ u \end{pmatrix} \quad f(r_1) = r_2$$

$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} e \\ f \end{pmatrix} = \begin{pmatrix} ax + by + e \\ cx + dy + f \end{pmatrix}$$

a, b, c, d, e, f  
costanti

$$\begin{cases} a \cdot t + b \cdot 1 + e = 1 \\ c \cdot t + d \cdot 1 + f = u \end{cases} \quad \forall t$$

deso trovare u dato t

$$at + (b+e-1) = 0 \quad \forall t \Rightarrow \begin{matrix} a=0 \\ b+e=1 \end{matrix}$$

$\forall u \in \mathbb{R}$  deso trovare s tale che

$$f \begin{pmatrix} 1 \\ u \end{pmatrix} = \begin{pmatrix} s \\ -1-s \end{pmatrix} \quad r_3: \begin{cases} x=s \\ y=-1-s \end{cases}$$

$$\begin{cases} a + bu + e = s \\ c + du + f = -1 - s \end{cases} \quad \forall s \Rightarrow c + du + f = -1 - bu - e - a$$

$$(d+b)u + c + f + a + e + 1 = 0 \quad \forall u$$

$$\begin{matrix} d+b=0 & c+f+a+e = -1 \\ \forall s \text{ deso trovare } t \text{ tale che} \end{matrix} \quad f \begin{pmatrix} s \\ -1-s \end{pmatrix} = \begin{pmatrix} t \\ 1 \end{pmatrix} \quad \forall s \begin{cases} as + b(-1-s) + e = t \\ cs + d(-1-s) + f = 1 \end{cases}$$

$$(c-d)s + f - d = 1 \quad \forall s \quad \begin{matrix} c-d=0 \\ f-d=1 \end{matrix}$$

$$\begin{cases} a=0 \\ b+e=1 \\ b+d=0 \\ c+f+a+e=-1 \\ c-d=0 \\ f-d=1 \end{cases}$$

$$\begin{cases} a=0 \\ c=d \\ b=-d \\ e=1+d \\ f=1+d \end{cases}$$

$$d+1+d+0+1+d=-1$$

$$3d = -3$$

$$d = -1$$

$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \end{pmatrix} = \begin{pmatrix} y \\ -x-y \end{pmatrix}$$

$$f \begin{pmatrix} t \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1-t \end{pmatrix} \begin{matrix} \uparrow \in r_1 \\ \uparrow \in r_2 \end{matrix}$$

$$f \begin{pmatrix} 1 \\ u \end{pmatrix} = \begin{pmatrix} u \\ -1-u \end{pmatrix} \begin{matrix} \uparrow \in r_2 \\ \uparrow \in r_3 \end{matrix}$$

$$f \begin{pmatrix} s \\ -1-s \end{pmatrix} = \begin{pmatrix} -1-s \\ 1 \end{pmatrix} \begin{matrix} \uparrow \in r_3 \\ \uparrow \in r_1 \end{matrix}$$

4.16

$$f(x) = Ax + b$$

$$f(r) = r'$$

senza punti fissi

$$r: y = x$$

$$r': y = -x$$

$$P = \begin{pmatrix} t \\ t \end{pmatrix}$$

$$P' = \begin{pmatrix} u \\ -u \end{pmatrix}$$

$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} e \\ f \end{pmatrix}$$

$\forall t \in \mathbb{R} \exists (i) u$  tale che

$$\begin{cases} at + bt + e = u \\ ct + dt + f = -u \end{cases}$$

$$(a+b+c+d)t + e+f = 0 \quad \forall t$$

$$f = -e \quad a + b + c + d = 0$$

$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} a & b \\ c & -(a+b+c) \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} e \\ -e \end{pmatrix}$$

$$-a(a+b+c) - bc \neq 0 \quad (\text{invertibilità})$$

$$F = \begin{pmatrix} x_F \\ y_F \end{pmatrix}$$

$$f \begin{pmatrix} x_F \\ y_F \end{pmatrix} = \begin{pmatrix} x_F \\ y_F \end{pmatrix}$$

$$\begin{cases} a x_F + b y_F + e = x_F \\ c x_F - (a+b+c) y_F - e = y_F \end{cases}$$

NON DEVE

$$\begin{cases} a x_F + b y_F + e = x_F \\ c x_F - (a+b+c) y_F - e = y_F \end{cases}$$

AVERE

SOLUZIONI!

$$\begin{cases} (a-1) x_F + b y_F = -e \\ c x_F - (a+b+c+1) y_F = e \end{cases}$$

$$\begin{cases} (a-1) x_F + b y_F = -e \\ c x_F - (a+b+c+1) y_F = e \end{cases}$$

$\rightarrow \text{rk}(A) = 1$

$$\begin{cases} -(a-1)(a+b+c+1) - bc = 0 \\ (a-1)e + ce \neq 0 \end{cases}$$

$$\begin{cases} -(a-1)(a+b+c+1) - bc = 0 \\ (a-1)e + ce \neq 0 \end{cases} \leftarrow \text{rk}(A') = 2 \quad \text{Rouche Capelli}$$

$$e(a+c-1) \neq 0$$

$$e \neq 0$$

$$e = 1 \text{ ad}$$

esempio

$$a+c \neq 1$$

$$b=0$$

$$a=1$$

$$c=1$$

$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 1 & -2 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$f \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x+1 \\ x-2y-1 \end{pmatrix}$$

$$f \begin{pmatrix} t \\ t \end{pmatrix} = \begin{pmatrix} t+1 \\ -(t+1) \end{pmatrix}$$

$$\begin{cases} x+1 = x \\ a-2y-1 = y \end{cases}$$

effettivamente non ha  
soluzioni

4.17

$$f \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} \cos \alpha & -\sin \alpha & 0 \\ \sin \alpha & \cos \alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x-1 \\ y+1 \\ z-2 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ b \end{pmatrix}$$

$$\begin{pmatrix} (x-1)\cos\alpha - (y+1)\sin\alpha + 1 \\ (x-1)\sin\alpha + (y+1)\cos\alpha - 1 \\ z-2+b \end{pmatrix} = \begin{pmatrix} \cos\alpha & -\sin\alpha & 0 \\ \sin\alpha & \cos\alpha & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \\ 2 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ b \end{pmatrix}$$

$$+ \begin{pmatrix} 1 - \cos\alpha - \sin\alpha \\ -1 + \cos\alpha - \sin\alpha \\ b \end{pmatrix}$$

Imponiamo  $f \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \\ 2 \end{pmatrix}$

$$\begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 - \cos\alpha - \sin\alpha \\ -1 + \cos\alpha - \sin\alpha \\ b \end{pmatrix} = \begin{pmatrix} 2 \\ -2 \\ 2 \end{pmatrix} \Rightarrow \begin{cases} 1 - \cos\alpha - \sin\alpha = 2 \\ -1 + \cos\alpha - \sin\alpha = -2 \\ (\cos^2\alpha + \sin^2\alpha = 1) \\ b+1 = 2 \end{cases}$$

$$b=1$$

$$\begin{cases} \cos\alpha + \sin\alpha = -1 \\ \cos\alpha - \sin\alpha = -1 \end{cases}$$

$$\begin{cases} \sin\alpha = 0 \\ \cos\alpha = -1 \end{cases} \quad \text{OK! } \alpha = \pi$$

$$f \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} 2 \\ -2 \\ 1 \end{pmatrix}$$

4.18

$$x=0 \quad \pi_1$$

$$y=0 \quad \pi_2$$

Isometria senza punti fissi t.c.  $f(\pi_1) = \pi_2$

rotat. di  $\frac{\pi}{2}$  intorno all'asse  $z$  + traslat. lungo  $z$

$$f \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} -y \\ x \\ z+1 \end{pmatrix}$$

$$P \in \Pi_1 \begin{pmatrix} 0 \\ t \\ u \end{pmatrix} \quad P' \in \Pi_2 \begin{pmatrix} v \\ 0 \\ w \end{pmatrix}$$

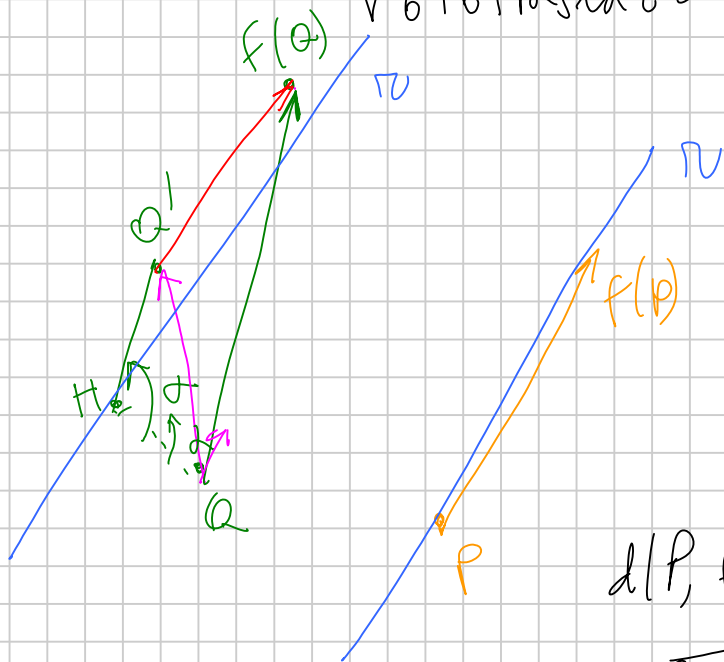
$$f \begin{pmatrix} 0 \\ t \\ u \end{pmatrix} = \begin{pmatrix} -t \\ 0 \\ u+1 \end{pmatrix} \leftarrow \in \Pi_2 \quad \begin{matrix} v = -t \\ w = u+1 \end{matrix}$$

$$\left. \begin{matrix} x = -y \\ y = x \\ z = z+1 \end{matrix} \right\} \text{impossibile!}$$

4.19

$$f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$$

rototraslazione asse



$$d(P, f(P)) = d(Q', f(Q)) \text{ diseg. } \downarrow \text{triangolare}$$

$$d(P, f(P)) = d(Q', f(Q)) \leq$$

$$\underbrace{d(Q, Q')} + d(Q, f(Q)) > 0$$

$$d(P, f(P)) < d(Q, f(Q))$$

## TEOREMA SPETTRALE

$\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix}$  simmetrica    verifica che  $\exists$  una base  
 ortogonale di autovettori

$\begin{pmatrix} 1 & 1 \\ 0 & 2 \end{pmatrix}$  non è simm.    la base di autovettori  
 ( $\& \exists$ ) non è ortogonale

$$\det \begin{pmatrix} 2-\lambda & 1 \\ 1 & 1-\lambda \end{pmatrix} = \lambda^2 - 3\lambda + 1 = 0$$

$$\lambda_{1,2} = \frac{3 \pm \sqrt{5}}{2}$$

$$\begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \frac{3 \pm \sqrt{5}}{2} \begin{pmatrix} x \\ y \end{pmatrix} \rightarrow \begin{cases} 2x + y = \frac{3 \pm \sqrt{5}}{2} x \\ x + y = \frac{3 \pm \sqrt{5}}{2} y \end{cases}$$

$$\begin{cases} \left(2 - \frac{3 + \sqrt{5}}{2}\right)x + y = 0 \\ x + \left(1 - \frac{3 + \sqrt{5}}{2}\right)y = 0 \end{cases} \quad \begin{cases} (1 + \sqrt{5})x + 2y = 0 \\ 2x + (-1 + \sqrt{5})y = 0 \end{cases}$$

$$\begin{pmatrix} -2 \\ 1 - \sqrt{5} \end{pmatrix}$$

$$\begin{pmatrix} -2 \\ 1 + \sqrt{5} \end{pmatrix}$$

ORTOGONALI  
OK

$$\begin{pmatrix} -2 & 1 - \sqrt{5} \end{pmatrix} \begin{pmatrix} -2 \\ 1 + \sqrt{5} \end{pmatrix} = 4 + 1 - 5 = 0$$



$$\det \begin{pmatrix} 1-\lambda & 1 \\ 0 & 2-\lambda \end{pmatrix} = \lambda^2 - 3\lambda + 2 = 0$$

$$\lambda_{1,2} = \frac{3 \pm 1}{2} \begin{cases} 1 \\ 2 \end{cases}$$

$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$  autovettore con  $\lambda = 1$   
 $\begin{pmatrix} 1 \\ 1 \end{pmatrix}$  autovettore con  $\lambda = 2$

non sono ortogonali

$$\begin{pmatrix} 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 1 \cdot 1 + 0 \cdot 1 = 1 \neq 0$$

5.2

$$\begin{pmatrix} 1 & i \\ -i & 1 \end{pmatrix} \quad (1-\lambda)^2 - 1 = 0$$

$$\lambda_1 = 0 \quad \lambda_2 = 2$$

$\begin{pmatrix} 1 \\ i \end{pmatrix}$  autovettore con  $\lambda_1 = 0$   
 $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$  autovettore con  $\lambda_2 = 2$

ortogonali

$$\begin{pmatrix} 1 & i \end{pmatrix}^* \cdot \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 1 & -i \end{pmatrix} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = 1 - 1 = 0$$