

ES:

$$\dot{x} = Ax \quad \xrightarrow{\text{EULERO}} \quad x_k = x_{k-1} + \overset{> 0}{h_{k-1}} A x_{k-1}$$

$$= \underbrace{(I + h_{k-1} A)}_B x_{k-1}$$

A inv

$$\left[\Rightarrow x=0 \text{ unica} \right. \\ \left. \text{conf ep} \right]$$

Pti uniti:

$$\cancel{x} = \cancel{x} + h_{k-1} A x$$

$$0 = h_{k-1} A x$$

$$\Rightarrow \boxed{x=0 \text{ e' l' UNICO}}$$

- Ip: A diagonalizz (semplifica, ma non e' neces per il ris...):

$$I + h_{k-1} A = I + h_{k-1} S \Lambda S^{-1} =$$

$$= S \underbrace{(I + h_{k-1} \Lambda)}_{\text{diag}(1+h_{k-1} \lambda_i)} S^{-1}$$

e' diagonalizz, e la matrice che realizza la diag e' S

- $h > 0$ dato:

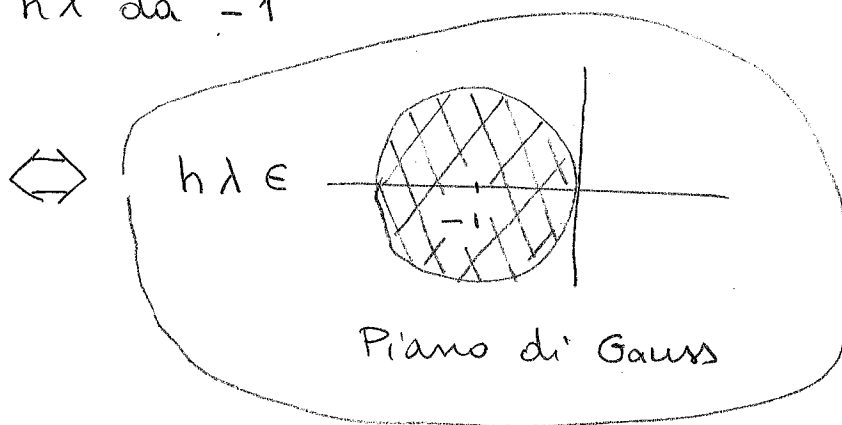
$\lambda \in \mathbb{C}$ autoval di A

$$\Leftrightarrow 1+h\lambda \text{ autoval di } I+hA$$

$$\left[\text{inoltre:} \right. \\ \left. \text{m.a.}(\lambda) = \text{m.a.}(1+h\lambda) \text{ \& } \text{mg}(\lambda) = \text{mg}(1+h\lambda) \right]$$

- $h > 0, \lambda \in \mathbb{C}$ dati:

$$|1 + h\lambda| = \underbrace{|h\lambda - (-1)|}_{\text{distanza di } h\lambda \text{ da } -1} \leq 1$$



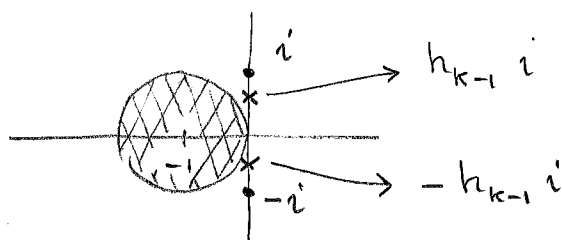
Oscill $\dot{x} = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} x$

- autovalori: $\lambda_1 = i, \lambda_2 = -i$
- $\text{re}(\lambda_k) = 0$ (E) $\text{ma}(\lambda_k) = \text{mq}(\lambda_k) = 1$

$\Rightarrow x=0$ è conf eq STABILE
(ma NON as stabile...)

Euler: $x_k = x_{k-1} + h_{k-1} \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} x_{k-1}$

- autovalori: $\lambda'_1 = 1 + h_{k-1} i; \lambda'_2 = 1 - h_{k-1} i$



INSTABILE
 $\forall h_{k-1} > 0$

Es: $\dot{x} = Ax$ — **FULERO IMPUGNATO** → $x_k = x_{k-1} + h_{k-1} A x_k$

A inv

⇒ $\exists!$ ep sia per ep dett che m discreto

⇒ $x_k = \underbrace{(I - h_{k-1} A)^{-1}}_B x_{k-1}$

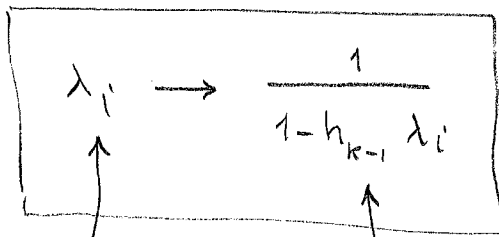
Ip: A diagonalizz...

• $I - h_{k-1} A = S (I - h_{k-1} \Lambda) S^{-1}$

⇒ ⇔ $\forall i, 1 - h_{k-1} \lambda_i \neq 0$

⇒ $(I - h_{k-1} A)^{-1} = S \underbrace{(I - h_{k-1} \Lambda)^{-1}}_B S$

= $\text{diag} \left(\frac{1}{1 - h_{k-1} \lambda_1}, \dots, \frac{1}{1 - h_{k-1} \lambda_m} \right)$



autov di A

autov di B, $\neq 0 \forall h_{k-1}$

• sistema discreto:

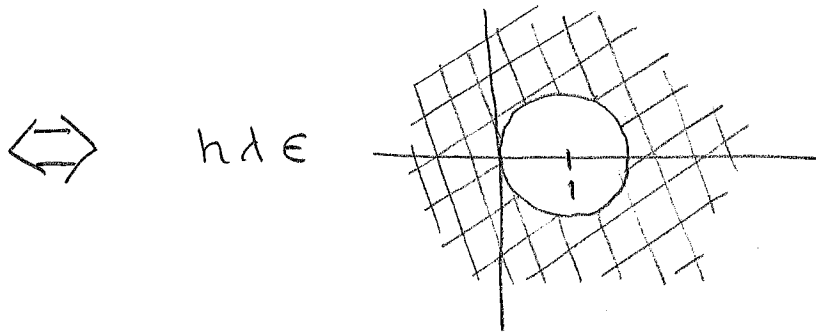
(1) $\exists \Leftrightarrow \forall k, \forall i: h_{k-1} \lambda_i \neq 1$

(2) B, se esiste, e' invertibile

• $h > 0, \lambda \in \mathbb{C}$ dati

$\left| \frac{1}{1 - h\lambda} \right| \leq 1 \Leftrightarrow |1 - h\lambda| = |h\lambda - 1| \geq 1$

distanza di $h\lambda$ da 1

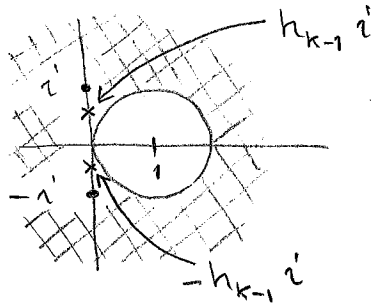


Piano di Gauss

Oscill

Euler implicitito:

- autovallori: $\lambda_1'' = \frac{1}{1 - h_{k-1} i}$, $\lambda_2'' = \frac{1}{1 + h_{k-1} i}$



AS. STABILE
 $\forall h_{k-1} > 0$