

OSS  $A \in \mathbb{C}^{n \times m}$ ,  $\sigma_1, \dots, \sigma_m$  v.s. di  $A$

$U, \Sigma, V$  decomp vs di  $A$

$U, \Sigma, V \in \mathbb{C}^{n \times n}$  t.c.  $A = U \Sigma V^H$

$\Rightarrow |\det A| = |\det U \det \Sigma \det(V^H)| = \sigma_1 \dots \sigma_m$

$A$  invert  $\Leftrightarrow$  tutti i vs sono  $\neq 0$

\* Studio di SISTEMI di EQ LIN \*

$A \in \mathbb{C}^{m \times k}$ ;  $U = (u_1, \dots, u_m)$ ,  $\Sigma$ ,  $V = (v_1, \dots, v_k)$  decomp vs

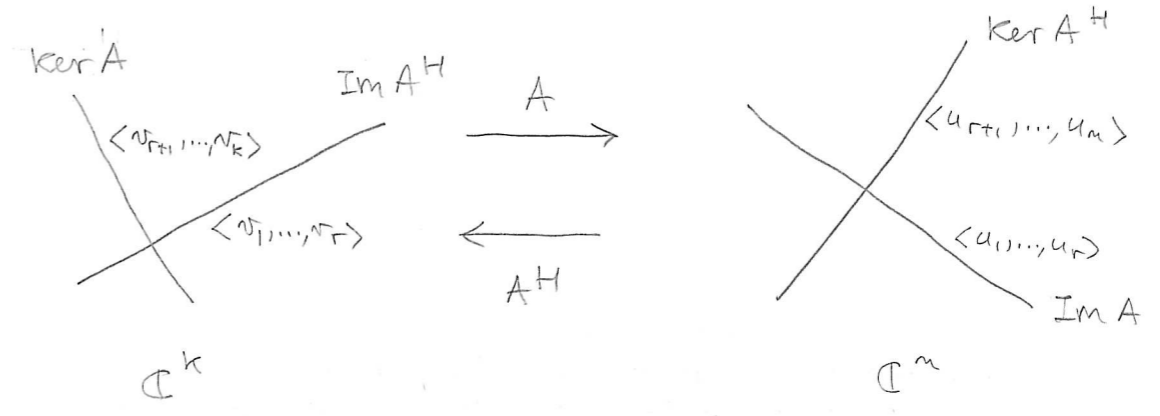
- 1)  $rk A = r$  (# vs non nulli)
- 2)  $v_{r+1}, \dots, v_k$  base su di  $\text{Ker } A \subset \mathbb{C}^k$
- 3)  $u_1, \dots, u_r$  base su di  $\text{Im } A \subset \mathbb{C}^m$

$V, \Sigma^H, U$  decomp vs di  $A^H (\Leftrightarrow$  vs  $A^H =$  vs  $A)$

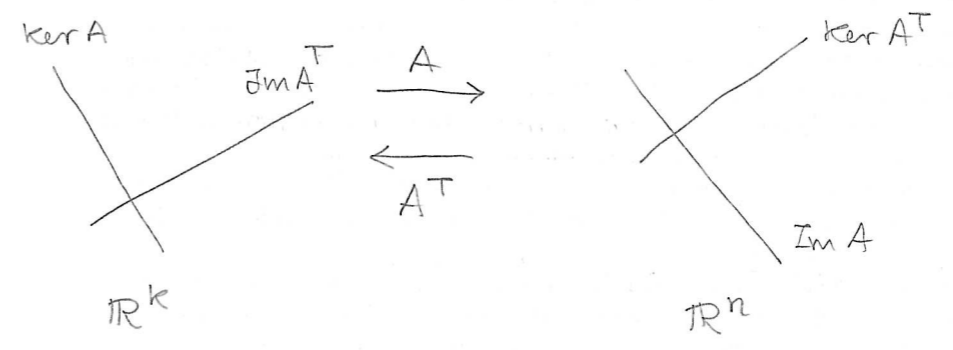
- 1)  $rk A^H = r$  (# vs non nulli)
- 2)  $u_{r+1}, \dots, u_m$  base su di  $\text{Ker } A^H \subset \mathbb{C}^m$
- 3)  $v_1, \dots, v_r$  base su di  $\text{Im } A^H \subset \mathbb{C}^k$

$\mathbb{C}^k = \langle v_1, \dots, v_r \rangle \oplus \langle v_{r+1}, \dots, v_k \rangle = \text{Im } A^H \oplus \text{Ker } A$

$\mathbb{C}^m = \langle u_1, \dots, u_r \rangle \oplus \langle u_{r+1}, \dots, u_m \rangle = \text{Im } A \oplus \text{Ker } A^H$



caso "reale":  $A \in \mathbb{R}^{m \times k}$ ;  $U, \Sigma, V$  ad elem reali...



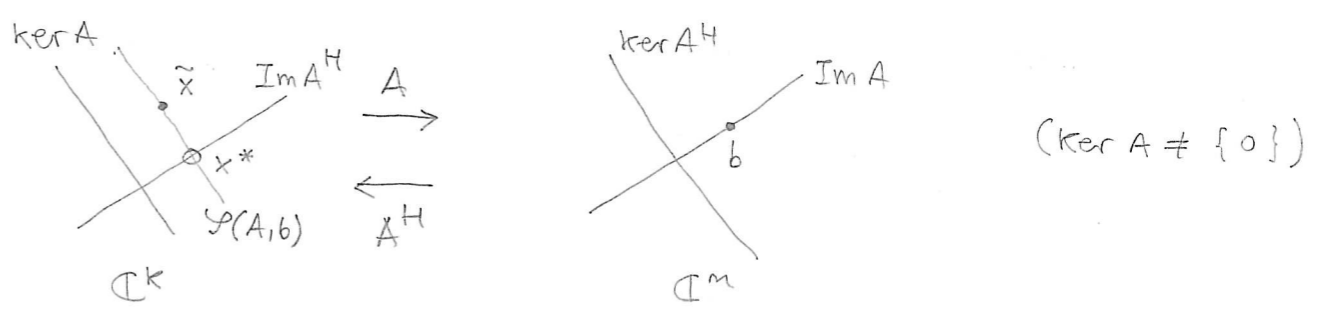
- $\mathbb{R}^k = \text{Im } A^T \oplus \text{Ker } A$
- $\mathbb{R}^m = \text{Im } A \oplus \text{Ker } A^T$

STRUTTURA dell'INS delle soluz

$A \in \mathbb{C}^{m \times k}$ ,  $b \in \mathbb{C}^m$

(1) se  $b \in \text{Im } A$ :

- $\mathcal{Y}(A, b) \neq \emptyset$
- $\tilde{x} \in \mathcal{Y}(A, b) \Rightarrow \mathcal{Y}(A, b) = \tilde{x} + \text{Ker } A$



( $\text{Ker } A \neq \{0\}$ )

- $\mathcal{Y}(A, b) \cap \text{Im} A^H$  ha un solo elem ( $x^*$ )
- $x^*$  è l'elem di  $\mathcal{Y}(A, b)$  di minima norma euclidea

(2) Se  $b \notin \text{Im} A \Rightarrow \mathcal{Y}(A, b) = \emptyset$

Es:  $A = \begin{bmatrix} 0 & 1 & 1 \\ 1 & 1 & 0 \end{bmatrix}$ ,  $b = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$  (in  $\mathbb{R}$ )

- $b \in \text{Im} A$ ,  $\tilde{x} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \in \mathcal{Y}(A, b)$

- $\mathcal{Y}(A, b) = \tilde{x} + \text{Ker} A = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \langle \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \rangle$   
 $= \left\{ x = \begin{bmatrix} 1+\lambda \\ -\lambda \\ \lambda \end{bmatrix}, \lambda \in \mathbb{R} \right\}$

- $y \in \mathcal{Y}(A, b)$ ,  $\|y\|^2 = (1+\lambda)^2 + 2\lambda^2$

$$F(\lambda) = (1+\lambda)^2 + 2\lambda^2$$

F assume val minimo per  $\lambda^* = -\frac{1}{3}$

e l'elem corrispondente  $x^* = \frac{1}{3} \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$

- $y \in \mathcal{Y}(A, b) \cap \text{Im} A^H \Leftrightarrow y \in \mathcal{Y}(A, b) \text{ e } y \perp \text{Ker} A$

$$\Leftrightarrow \left( \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \lambda \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right) \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} = 0 \Leftrightarrow \lambda = -\frac{1}{3} \dots$$

### SOLUZIONI nel SENSO dei 'MINIMI QUADRATI'

- $A \in \mathbb{C}^{m \times k}$ ,  $b \in \mathbb{C}^m$

$$F: \mathbb{C}^k \rightarrow \mathbb{R} \text{ t.c. } F(x) = \|Ax - b\|^2$$

def  $y \in \mathbb{C}^k$  che rende minimo il valore di  $F$ , ovvero t.c.  $\forall w \in \mathbb{C}^k, \|Ay - b\|^2 \leq \|Aw - b\|^2$  si chiama SOLUZIONE di  $Ax = b$  NEL SENSO dei MINIMI QUADRATI

L'insieme delle soluz di  $Ax = b$  nel senso dei m.q. si indica con

$$\mathcal{Y}_{MQ}(A, b) \subset \mathbb{C}^k$$

Es:  $A = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 0 & 0 \end{bmatrix}$ ,  $b = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$  (in  $\mathbb{R}$ )

- $b \notin \text{Im} A$ ,  $F: \mathbb{R}^2 \rightarrow \mathbb{R}$

- $F(x) = \|Ax - b\|^2 = \left\| \begin{bmatrix} x_1 \\ x_2 \\ -1 \end{bmatrix} \right\|^2 = x_1^2 + x_2^2 + (-1)^2$

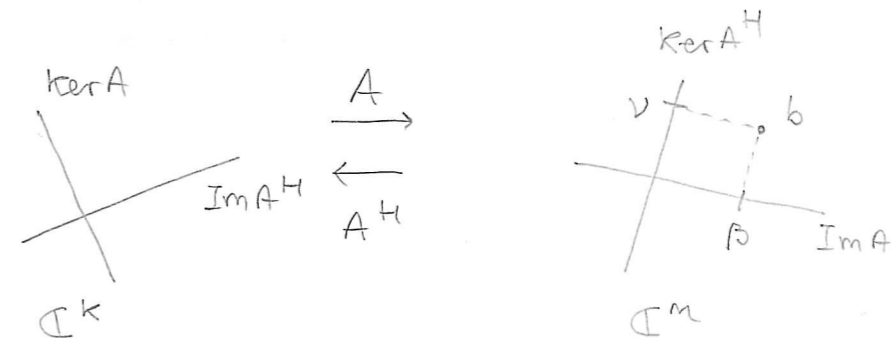
(1) se  $b \in \text{Im} A$  allora  $\mathcal{Y}_{MQ}(A, b) = \mathcal{Y}(A, b)$

(in fatti:  $x \in \mathcal{Y}(A, b) \Rightarrow F(x) = 0$  e  $F \geq 0 \dots$ )

(2) se  $b \notin \text{Im} A$ :

- $\mathcal{Y}(A, b) = \emptyset$

- $b = \beta + v$ ,  $\beta \in \text{Im} A$ ,  $v \in \text{Ker} A^H$



Es:  $A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \in \mathbb{R}^{3 \times 4}$ ,  $b = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \in \mathbb{R}^3$

•  $\text{Im } A = \left\langle \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \right\rangle$ ,  $\text{Ker } A = \left\langle \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\rangle$

•  $\text{Ker } A^H = \left\langle \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\rangle$

•  $b = \underbrace{\beta_1 \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \beta_2 \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}}_{\beta \in \text{Im } A} + \underbrace{\nu_1 \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}}_{\nu \in \text{Ker } A^H}$

$\Rightarrow \beta_1 = 0, \beta_2 = \nu_1 = 1$  ovvero

$b = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} = \beta + \nu$

•  $\mathcal{Y}_{MQ}(A, b) = \mathcal{Y}(A, \beta)$

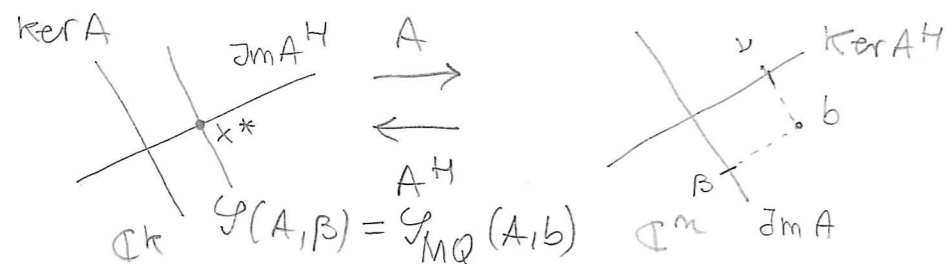
$\forall x \in \mathbb{C}^k: \|Ax - b\|^2 = \|Ax - \beta - \nu\|^2$   
 $= \|Ax - \beta\|^2 + \|\nu\|^2$

dunque  $\|Ax - b\|^2$  assume valore minimo

$\Leftrightarrow \|Ax - \beta\|^2$  assume valore minimo

ovvero  $\mathcal{Y}_{MQ}(A, b) = \mathcal{Y}_{MQ}(A, \beta) = \mathcal{Y}(A, \beta)$

perché  $\beta \in \text{Im } A$



•  $\mathcal{Y}(A, \beta) \cap \text{Im } A^H$  ha un solo elemento,  $x^*$ , ed è l'elem di  $\mathcal{Y}_{MQ}(A, b)$  di minima norma euclidea.

Es:  $A = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \in \mathbb{R}^{3 \times 4}$ ,  $b = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \in \mathbb{R}^3$

determina  $\mathcal{Y}_{MQ}(A, b)$ .

•  $b \notin \text{Im } A \Rightarrow \mathcal{Y}(A, b) = \emptyset$

•  $b = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} = \beta + \nu$

•  $\tilde{x} = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} \in \mathcal{Y}(A, \beta)$

$\Rightarrow \mathcal{Y}_{MQ}(A, b) = \mathcal{Y}(A, \beta) = \tilde{x} + \text{Ker } A = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \left\langle \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\rangle$

•  $x \in \mathcal{Y}_{MQ}(A, b) \cap \text{Im } A^H \Leftrightarrow$   
 $x \in \mathcal{Y}_{MQ}(A, b) \oplus x \perp \text{Ker } A$

$\Leftrightarrow x = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + \alpha_1 \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + \alpha_2 \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix}$  e  $x \cdot \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} = x \cdot \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} = 0$

$\Leftrightarrow \alpha_1 = 0, \alpha_2 = 0$  q.d.  $x^* = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \end{bmatrix}$