

$\int_a^b \gamma(t) dt \approx \sum_{i=0}^{n-1} \gamma(\xi_i) (t_{i+1} - t_i)$

Somme di Riemann di γ

$$\left| \int_a^b \gamma(t) dt \right| \leq \int_a^b |\gamma(t)| dt$$

scalare

$$\begin{pmatrix} \sum_{i=0}^{n-1} \gamma_1(\xi_i) (t_{i+1} - t_i) \\ \vdots \\ \sum_{i=0}^{n-1} \gamma_n(\xi_i) (t_{i+1} - t_i) \end{pmatrix}$$

$$= \sum_{i=0}^{n-1} (t_{i+1} - t_i) \begin{pmatrix} \gamma_1(\xi_i) \\ \vdots \\ \gamma_n(\xi_i) \end{pmatrix}$$

$\in \mathbb{R}^n$ $a < b$

$t_0 < t_1 < \dots < t_n$

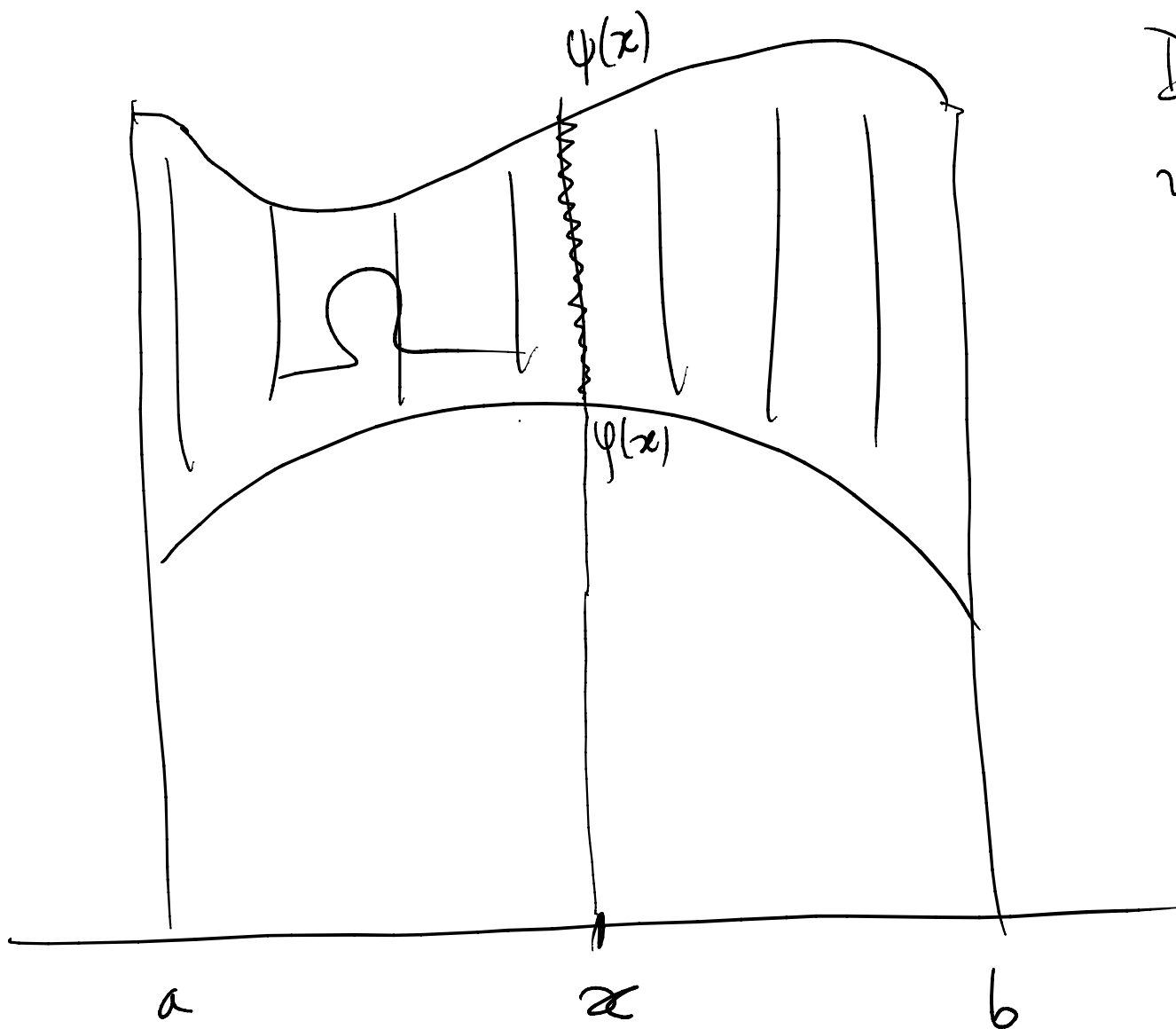
$$\left| \int_a^b \gamma(t) dt \right| \leq \sum_{i=0}^{n-1} (t_{i+1} - t_i) \overbrace{|\gamma(\xi_i)|}^{\text{scalare}} \sim \int_a^b |\gamma(t)| dt$$

somme di Riemann di $|\gamma|$

$f \leq f $	$a < b$
--------------	---------

$$\int_a^b f \leq \int_a^b |f| \quad \underline{|f| \leq |f|}$$

$\int_a^b = \int -b \leq \int -a$

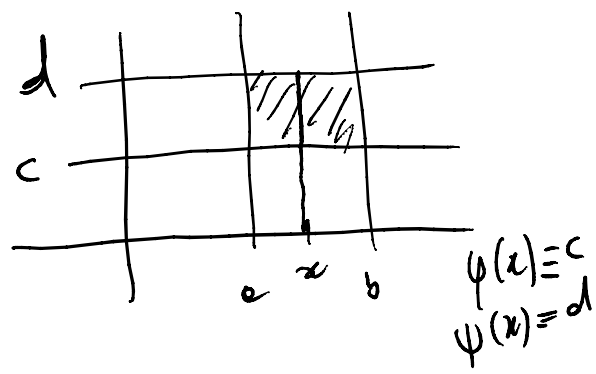


Domini
 normali
 rispetto ad x

$$x \in [a, b]$$

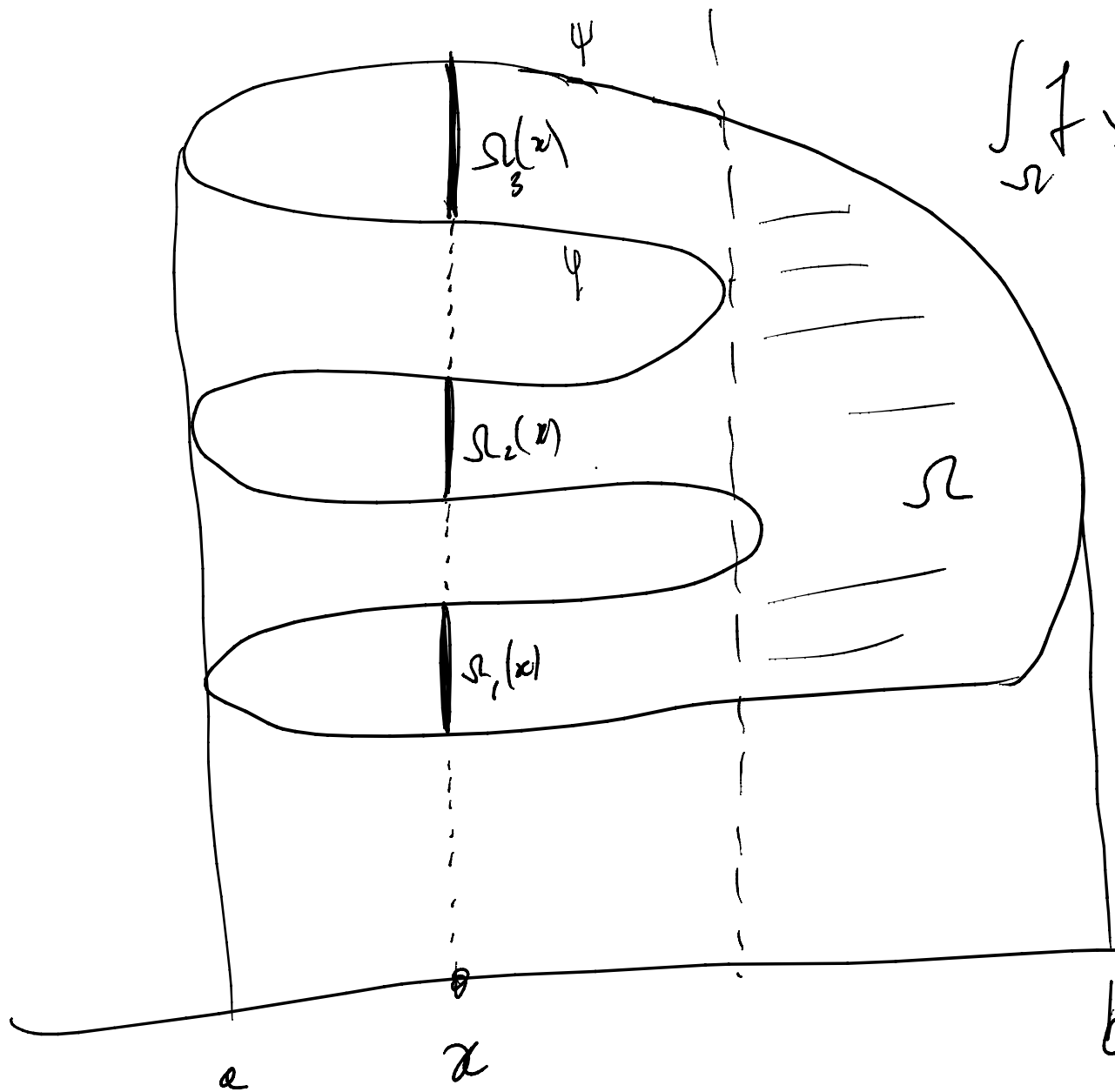
$$y \in [\varphi(x), \psi(x)]$$

$$[a, b] = \prod_x \Omega \quad \Omega(x) = [\varphi(x), \psi(x)]$$



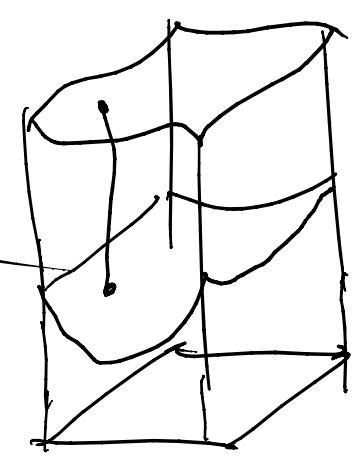
$$\varphi(x) = c$$

$$\psi(x) = d$$



$$\int_{\Omega} f = \int_a^b dx \int_{\Omega_1(x)} f(x,y) dy +$$

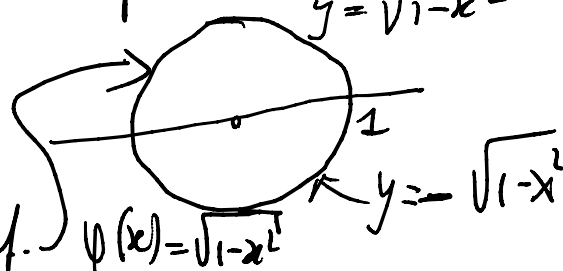
$$+ \int_{\Omega_2(x)} + \int_{\Omega_3(x)}$$



Estremi di $f: \Omega \rightarrow \mathbb{R}$ con Ω chiuso e limitato

① Studiare separatamente i punti interni
Su $\overset{\circ}{\Omega}$ ogni estremo (anche solo locale) verifica
la condizione d'Euler $\nabla f(x_0) = 0$

② Studiare gli estremi su $\partial\Omega$ (supporto unip. regione)

Le $\partial\Omega$ si può decomporre in grafici cartesiani (pezzi di
bordo del tipo $(x, \varphi(x))$ e funzioni decise
 $x \rightarrow f(x, \varphi(x))$ 1 variabile e vanno gli estremi relativi di f
sulle sezioni conv. 

b) $\exists \gamma: [a, b] \rightarrow \partial\Omega$ surjective
 $x \rightarrow f(\gamma(x))$ assume tutti i valori di f in $\partial\Omega$

c) $\exists g: \mathbb{R}^2 \rightarrow \mathbb{R}: \partial\Omega = \{(x, y): g(x, y) = 0\}$

Lagrange estremi (lbcv) di $f(x, y) + \lambda g(x, y) = \phi$

$$\phi_x \left\{ \begin{array}{l} f_x + \lambda g_x = 0 \\ f_y + \lambda g_y = 0 \\ g(x, y) = 0 \end{array} \right.$$

$$\phi_y$$

$$\phi_\lambda$$

$$g(x, y) = 0 \leftarrow$$

\updownarrow

nel caso $\Omega = \{x^2 + y^2 \leq 1\}$

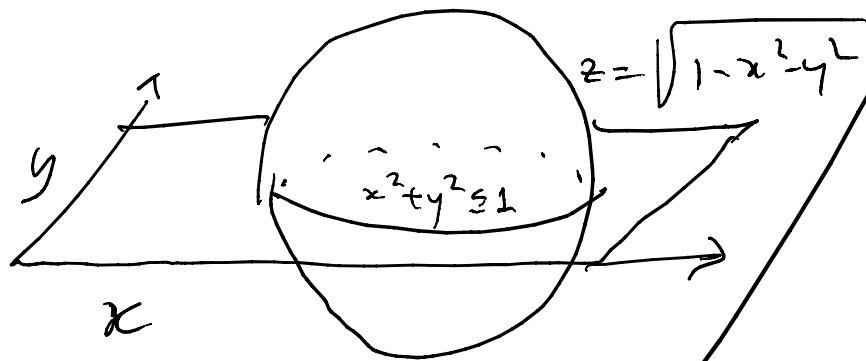
a) $(x, \sqrt{1-x^2}) \quad x \in [-1, 1]$

$(x, -\sqrt{1-x^2}) \quad x \in [-1, 1]$

b) $(\cos t, \sin t) \quad t \in [0, 2\pi]$

c) $g(x, y) = x^2 + y^2 - 1$

$$\Omega \{ x^2 + y^2 + z^2 \leq 1 \}$$



$$\partial\Omega$$

a) $(x, y, \sqrt{1-x^2-y^2})$ with $\underline{x^2+y^2 \leq 1}$
 $(x, y, -\sqrt{\quad})$ "

b) $(\sin\theta \cos\varphi, \sin\theta \sin\varphi, \cos\theta)$
 $\theta \in [0, \pi] \quad \varphi \in [0, 2\pi]$

$(x, y) \rightarrow f(x, y, \sqrt{1-x^2-y^2})$
 $(x, y) \in \overline{B(0,0)}_1$

c) $g(x, y, z) = x^2 + y^2 + z^2 - 1$
 \Downarrow
 $x^2 + y^2 + z^2 = 1$
 $f_x + 2\lambda x = 0$
 $f_y + 2\lambda y = 0$
 $f_z + 2\lambda z = 0$

f is continuous at x_0 $\Leftrightarrow \lim_{w \rightarrow 0} |f(x_0 + w) - f(x_0)| = 0$

$$f(x_0 + w) - f(x_0) = \underbrace{f(x_0 + w) - f(x_0) - A(w)}_{\text{error}} + A(w) =$$

$$= |w| \frac{f(x_0 + w) - f(x_0) - A(w)}{|w|} + A(w)$$

$w \neq 0$
 $w \rightarrow 0$
 $w \rightarrow 0$
 $w \rightarrow 0$
 $w \rightarrow 0$

$A = df$


$$= |w| \frac{A(w)}{|w|} \text{ o-imp.}$$

$$A(w) = A(\sum w_i e_i) = \sum w_i \underbrace{A(e_i)}_{\in \mathbb{R}} \xrightarrow{w \rightarrow 0} 0$$

because $w \rightarrow 0$
 $w_i \rightarrow 0 \forall i$

1) A è irrotazionale se $\forall \gamma$ chiusa $\int_{\gamma} A = 0$ (C.N.S. se $A \in C^0$)
in Ω in Ω

2) Ω è semplicemente connesso allora ogni γ chiusa in Ω è deformabile in una σ costante

3) Th. inversa omotopica se γ e σ sono omotopiche in Ω e A è irrotazionale in $\Omega \Rightarrow \int_{\gamma} A = \int_{\sigma} A$
Sul Prop. An 2


4) da 2) e 3) $\int_{\gamma} A = \int_{\sigma} A = 0$
 \downarrow σ è costante e $\dot{\sigma} = 0$

$\Rightarrow \int_{\text{ogni curva chiusa}} A = 0 \Leftrightarrow 1 \Leftrightarrow \text{tesi.}$

$$\gamma(t_{i+1}) - \gamma(t_i) \stackrel{\text{Fund.}}{=} \int_{t_i}^{t_{i+1}} \dot{\gamma}(t) dt$$

///

$$\gamma_1(t_{i+1}) - \gamma_1(t_i) = \int_{t_i}^{t_{i+1}} \dot{\gamma}_1(t) dt$$

⋮

$$\gamma_N(t_{i+1}) - \gamma_N(t_i) = \int_{t_i}^{t_{i+1}} \dot{\gamma}_N(t) dt$$

$$f(b) - f(a) = \int_a^b f'(x) dx$$

Se f' est continue sur $[a, b]$

$\dot{\gamma}_1$ Lie continue in $[t_i, t_{i+1}]$

$\dot{\gamma}_N$ Lie continue sur $[t_i, t_{i+1}]$

$$\gamma \in C^1 \Rightarrow \dot{\gamma}_i \in C^0 \quad \forall i = 1, \dots, N$$



area $(1,0)$ raggio 1

$\frac{\pi}{6}$ zona

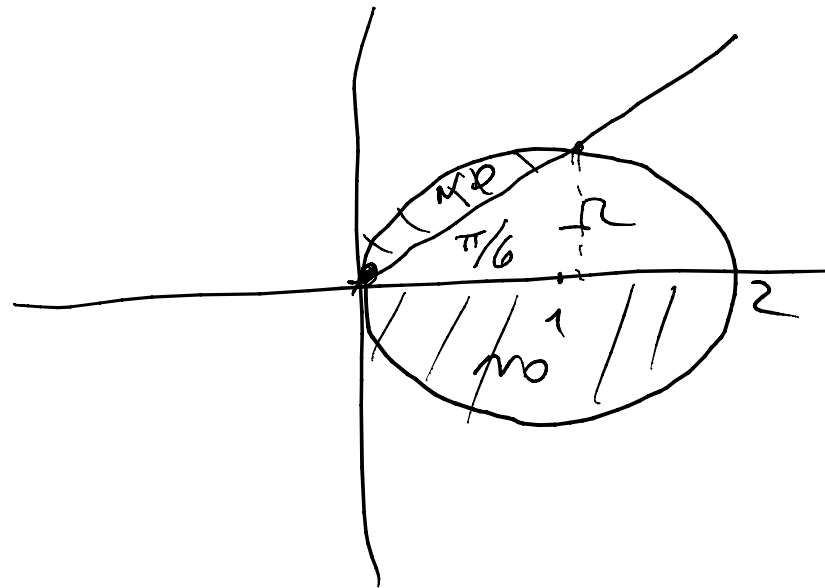
$$\int_{\Omega} 1 \, dx \, dy = \int_0^{\frac{\pi}{6}} d\theta \int_0^{\rho} p \, dp =$$

jacob.

$$= \int_0^{\frac{\pi}{6}} \frac{1}{2} (1 + \cos 2\theta) \, d\theta = \int_0^{\frac{\pi}{6}} 1 + \cos 2\theta \, d\theta =$$

$$\underline{2 \cos^2 \theta - 1 = \cos 2\theta}$$

$$\boxed{0 < \rho}$$



$$(x-1)^2 + y^2 \leq 1$$

$$x^2 + y^2 - 2x + 1 \leq 1$$

$$\rho^2 \leq 2\rho \cos \theta$$

$$\Downarrow \Rightarrow \rho < 2 \cos \theta$$

$$(4x^2 + 3y^2)^{-\frac{1}{2}} (4x, 3y)$$

dom A = $\mathbb{R}^2 \setminus \{(0,0)\}$
CONNESSO

$$\left. \begin{aligned} f_x &= \frac{4x}{\sqrt{4x^2 + 3y^2}} \\ f_y &= \frac{3y}{\sqrt{4x^2 + 3y^2}} \end{aligned} \right\} \Rightarrow f = \int \frac{4x \, dx}{\sqrt{4x^2 + 3y^2}} = \frac{1}{2} \int \frac{d_x(4x^2 + 3y^2)}{\sqrt{4x^2 + 3y^2}} =$$

$$(4x^2 + 3y^2)_x = 8x$$

$$= \frac{1}{2} \int \frac{dt}{\sqrt{t}} = \frac{1}{2} \int t^{-\frac{1}{2}} dt =$$

$t = 4x^2 + 3y^2$

$$= \frac{1}{2} \left[\frac{1}{\frac{1}{2}} t^{\frac{1}{2}} \right] = \sqrt{4x^2 + 3y^2} + c(y)$$

$$f_y = c'(y) + \frac{3y}{\sqrt{4x^2 + 3y^2}}$$

\Downarrow

$$c'(y) = 0 \Rightarrow c = \text{cost.}$$

$$f(x,y) = \sqrt{4x^2 + 3y^2} + C$$

$$\underline{\lambda} |x|^2 \leq \underbrace{\sum_{i,j} a_{ij} x_i x_j}_{\alpha(x)} \leq \underline{\Lambda} |x|^2$$

Se $\alpha(x)$ é definita $> 0 \iff \lambda > 0$

$$\alpha(x) \geq \lambda |x|^2$$



$+ \infty$

Seid th. compare

$\alpha \rightarrow +\infty$

lim
 $x \rightarrow \infty$

$|x| \rightarrow +\infty$

α def $> 0 \iff$ def $\Lambda < 0$

$$\alpha(x) \leq \underbrace{\underline{\Lambda} |x|^2}_{\substack{< 0 \\ \downarrow \\ +\infty}}$$

$-\infty$

comp. $\alpha(x) \rightarrow -\infty$

① α indefinito $\Leftrightarrow \lambda < 0 \quad \wedge > 0$

se u è un autovettore di λ }
e v è un autov. di λ^{-1} } $\left. \begin{array}{l} \text{di norme 1} \\ \text{accoppiate} \end{array} \right\}$

$$\alpha(u) = \lambda \quad \alpha(v) = \lambda^{-1}$$

$$\lim_{t \rightarrow +\infty} \alpha(tu) = \lambda t^2 \rightarrow -\infty$$

$\lambda < 0$

$$\lim_{t \rightarrow +\infty} \alpha(tv) = t^2 \lambda \rightarrow +\infty$$

$\lambda > 0$

$$|tu| \rightarrow +\infty$$

$$|tv| \rightarrow +\infty$$

il $\lim_{\infty} \alpha$ NON esiste

Caso semi-definito

$$\alpha \text{ semi-def. } \geq 0 \quad \lambda = 0 \quad \Lambda > 0$$

u vettore nelle auto-spazi di $\lambda = 0$

v u u u u Λ

$$\alpha(u) = 0$$

$$\alpha(v) = \Lambda \geq 0$$

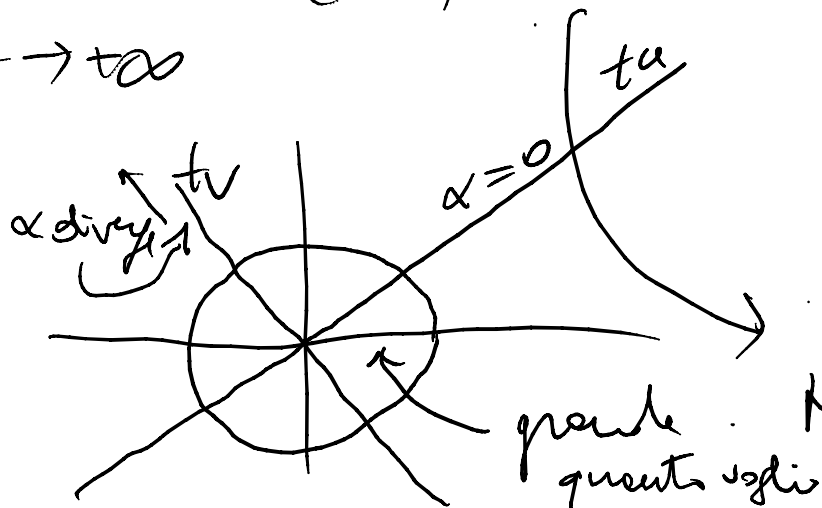
$$\lim_{\infty} 4x^2 + 3y^2$$

$$\begin{pmatrix} 4 & 0 \\ 0 & 3 \end{pmatrix}$$

$$\text{def. } > 0$$

$$\lim_{t \rightarrow +\infty} \alpha(tu) = 0$$

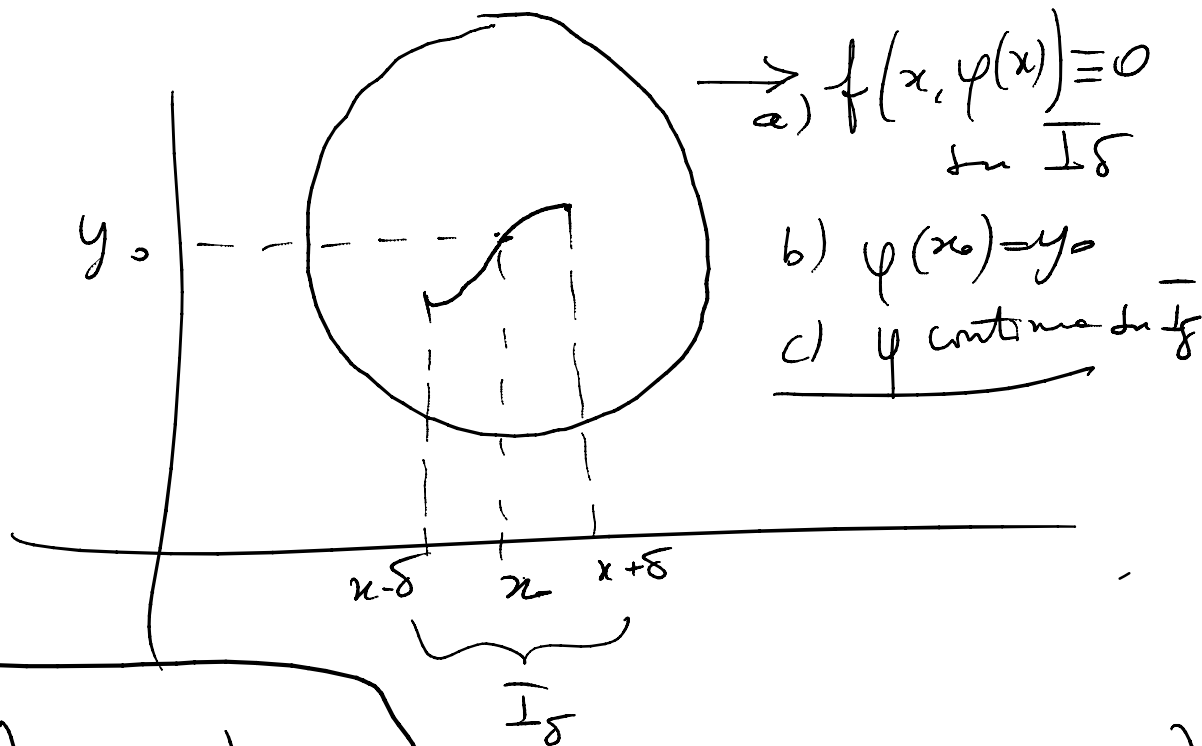
$$\lim_{t \rightarrow +\infty} \alpha(tv) = \lim_{t \rightarrow +\infty} t^2 \Lambda = +\infty$$



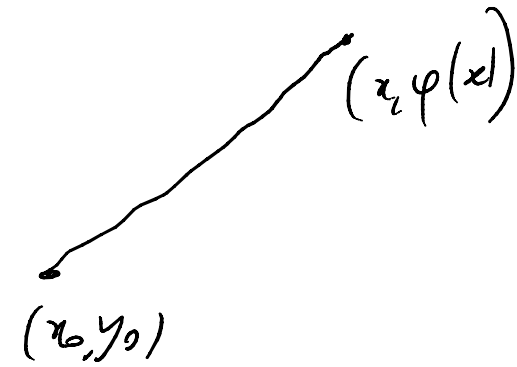
NON ESISTE

$$f \in C^1(B_p(x_0, y_0))$$

$$f(x, \varphi(x)) - f(x_0, \varphi(x_0)) =$$



$$= f_x \left(\underbrace{x_0 + \xi(x-x_0)}_{x_0}, \underbrace{\varphi(x_0) + \xi(\varphi(x) - \varphi(x_0))}_{\varphi(x_0)} \right) (x-x_0) + f_y(\dots) (\varphi(x) - \varphi(x_0))$$



$$\frac{\varphi(x) - \varphi(x_0)}{x - x_0} = - \frac{f_x}{f_y} (\dots)$$

$$h(x) = f(x, \varphi(x))$$

$$h(x) - h(x_0) = h'(\xi) (x - x_0) \quad \xi \in [x_0, x]$$

$$\int_{\Omega} f_x dx dy = \int_{\partial\Omega^+} f v_1 ds$$

$$\int_{\Omega} f_y dx dy = \int_{\partial\Omega^+} f v_2 ds$$

$$\int_{\Omega} f dx dy = \int_{\partial\Omega^+} f dy$$

$$\int_{\Omega} f dx dy = - \int_{\partial\Omega^+} f dx$$

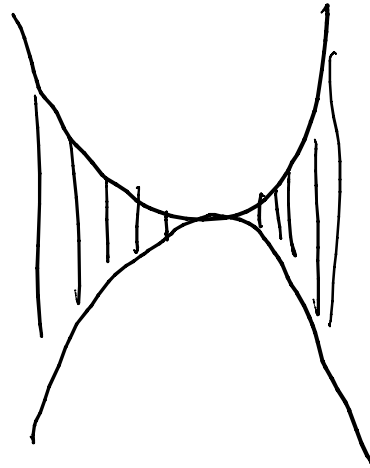
$$A = \begin{pmatrix} A_1 \\ A_2 \end{pmatrix}$$

$$\int_{\Omega} \underbrace{(A_1)_{x_1} + (A_2)_{x_2}}_{\text{div } A} dx dy = \int_{\partial\Omega^+} \underbrace{A_1 \cdot v_1 + A_2 \cdot v_2}_{\substack{A \cdot v \\ \text{prodotto} \\ \text{scalare}}} ds$$

$$\{ |y| \leq x^2 \}$$

$$-x^2 \leq y \leq x^2$$

$$\{(x, y) : -x^2 < y < x^2\}$$



$$|a| < 1$$

$$-1 < a < 1$$

$$|y| \leq |x|$$



$$-|x| \leq y \leq |x|$$

