

_____ (Cognome)

MARCO _____ (Nome)

_____ (Numero di matricola)

PRIMA PARTE

PUNTEGGIO : risposta mancante = 0 ; risposta esatta = +1 risposta sbagliata = -1
calcoli e spiegazioni non sono richiesti

- Sia $z = 4 \cdot e^{i\frac{2\pi}{3}}$. Scrivere z nella rappresentazione cartesiana $z = x + iy$: $z =$

$-2 + i 2\sqrt{3}$

- $z = 2 - i, w = 3 - 2i \Rightarrow \operatorname{Re}(z \cdot w) =$

4

Dati W e Z i seguenti sottospazi di \mathbb{R}^3 :

$W = \left\{ \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \in \mathbb{R}^3 : x_1 - 2x_2 + x_3 = 0 \right\}, Z = \left\langle \begin{pmatrix} 1 \\ 5 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 3 \\ 2 \end{pmatrix} \right\rangle.$

- Determinare una base di $W \cap Z$

$\left\{ \begin{pmatrix} 5 \\ 9 \\ 13 \end{pmatrix} \right\}$

• $A = \begin{pmatrix} 4 & 5 & 1 & 1 \\ 4 & 5 & 1 & 1 \\ 4 & 5 & 1 & 1 \\ 4 & 5 & 1 & 1 \\ 4 & 0 & 0 & 0 \end{pmatrix}$

$\Rightarrow \dim(\operatorname{Ker}(\mathcal{L}_A)) =$

2

$\operatorname{rg}(A) =$

2

• $\det \begin{pmatrix} 0 & 2 & 0 & 2 \\ 3 & 1 & 1 & 1 \\ 0 & 1 & 1 & 1 \\ 1 & 0 & 0 & 3 \end{pmatrix} =$

-18

• $A = \begin{pmatrix} 1 & -5 \\ 1 & 1 \end{pmatrix} \Rightarrow A$ è diagonalizzabile

vero ~~falso~~

• $A = \begin{pmatrix} 2 & 3 \\ 0 & 1 \end{pmatrix} \Rightarrow A^{-1} = \begin{pmatrix} 1 & -3 \\ 0 & 1 \end{pmatrix}$

• $A = \begin{pmatrix} 2 & -1 & 1 \\ -1 & 1 & 1 \end{pmatrix}, B = \begin{pmatrix} 1 & 1 \\ 1 & 0 \\ 2 & -1 \end{pmatrix} \Rightarrow A \cdot B = \begin{pmatrix} 3 & 1 \\ 2 & 2 \end{pmatrix}$

• Sia $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ lineare. Sapendo che $f \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}, f \begin{pmatrix} 1 \\ 4 \end{pmatrix} = \begin{pmatrix} 9 \\ 7 \end{pmatrix}$, allora $f \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 6 \\ 1 \end{pmatrix}$

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①

Treccia soluzioni

$$\textcircled{1} \quad \begin{cases} z^3 = -8 \cdot |z| \cdot \bar{z} \\ |z - 4i| \leq |z| \end{cases}$$

1^a eq. $z = \rho \cdot e^{i\vartheta} \rightarrow z^3 = \rho^3 \cdot e^{i3\vartheta}$
 $|z| = \rho$
 $\bar{z} = \rho \cdot e^{-i\vartheta}$

$$-8 = 8 \cdot e^{i\pi}$$

$$z^3 = -8|z|\bar{z} \Leftrightarrow \rho^3 \cdot e^{i3\vartheta} = 8 \cdot \rho^2 \cdot e^{i(\pi - \vartheta)}$$

$$\Leftrightarrow \begin{cases} \rho^3 = 8\rho^2 \\ 3\vartheta = \pi - \vartheta + 2k\pi, \quad k \in \mathbb{Z} \end{cases}$$

SOL. DISTINTE

$$\begin{cases} \rho = 0 \\ (z = 0) \end{cases} \quad \begin{cases} \rho = 8 \\ \vartheta = \frac{\pi + 2k\pi}{4}, \quad k = 0, 1, 2, 3 \end{cases}$$

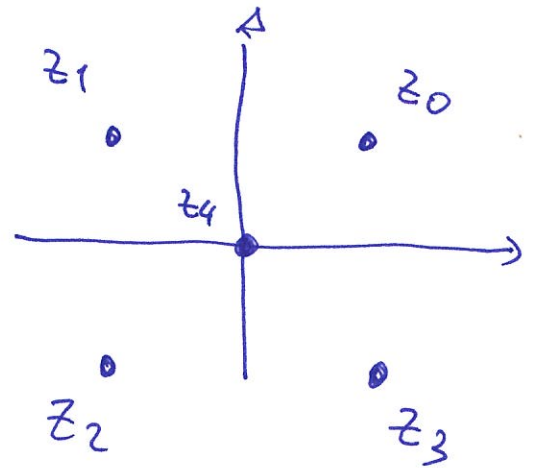
$$z_0 = 4\sqrt{2} + i 4\sqrt{2}$$

$$z_1 = -4\sqrt{2} + i 4\sqrt{2}$$

$$z_2 = -4\sqrt{2} - i 4\sqrt{2}$$

$$z_3 = 4\sqrt{2} - i 4\sqrt{2}$$

$$z_4 = 0$$



rep: $|z - 4i| \leq |z|$

$$z = x + iy$$

$$z - 4i = x + i(y - 4)$$

$$|z - 4i| \leq |z| \Leftrightarrow \sqrt{x^2 + (y - 4)^2} \leq \sqrt{x^2 + y^2}$$

$$\Leftrightarrow 16 - 8y \leq 0$$

$$\Leftrightarrow \begin{cases} y \geq 2 \\ x \text{ qualsiasi} \end{cases}$$

SOLUZIONI SISTEMA: z_0 , z_1
" " " "
 $4\sqrt{2} + i 4\sqrt{2}$ $-4\sqrt{2} + i 4\sqrt{2}$

$$\textcircled{2} \quad A_t = \begin{pmatrix} t & 2 & 0 \\ 1 & 1 & 1 \\ 0 & 4 & -t \end{pmatrix}$$

i) A_t matrice 3×3

$$\det(A_t) = t^2 + 2t$$

$$\text{QUINDI } \det(A_t) \neq 0 \Leftrightarrow t \neq 0, -2$$

$$t \neq 0, -2 \quad \begin{cases} \text{rg}(A_t) = 3 \\ \dim(\text{Ker}) = 3 - 3 = 0 \end{cases}$$

$$t=0: \quad A_{t=0} = \begin{pmatrix} 0 & 2 & 0 \\ 1 & 1 & 1 \\ 0 & 4 & 0 \end{pmatrix}$$

$$M = \begin{pmatrix} 0 & 2 \\ 1 & 1 \end{pmatrix} \text{ he } \det \neq 0 \Rightarrow$$

$$\begin{cases} \text{rg}(A) = 2 \\ \dim(\text{Ker}) = 3 - 2 = 1 \end{cases}$$

$$t=-2: \quad A_{t=-2} = \begin{pmatrix} -2 & 2 & 0 \\ 1 & 1 & 1 \\ 0 & 4 & 2 \end{pmatrix}$$

$$M = \begin{pmatrix} 1 & 1 \\ 0 & 4 \end{pmatrix} \text{ he } \det \neq 0 \Rightarrow$$

$$\begin{cases} \text{rg}(A) = 2 \\ \dim(\text{Ker}) = 3 - 2 = 1 \end{cases}$$

(4)

$$ii) \quad A_t \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 6 \\ 2 \\ 4 \end{pmatrix}$$

$$t \neq 0, -2 \quad \text{rg}(A_t) = 3$$

$$\text{rg}(A_t) \leq \text{rg}(A_t : b) \leq 3 \quad \Rightarrow \quad \text{rg}(A_t) = \text{rg}(A_t : b) = 3$$

$\Rightarrow \exists!$ SOLUZIONE

caso particolare:

$$\underline{t=0}: \quad \text{rg}(A_t) = 2 \quad \text{rg}(A_t : b) = 3$$

$$\text{poiché } \det \begin{pmatrix} 2 & 0 & 6 \\ 1 & 1 & 2 \\ 4 & 0 & 4 \end{pmatrix} \neq 0$$

\Rightarrow non \exists SOLUZIONE

$$t = -2: \quad \text{rg}(A_t) = 2 \quad \text{rg}(A_t : b) = 3$$

$$\text{poiché } \det \begin{pmatrix} -2 & 2 & 6 \\ 1 & 1 & 2 \\ 0 & 4 & 4 \end{pmatrix} \neq 0$$

\Rightarrow non \exists SOLUZIONE

iii) $t=0$

$$A_{t=0} : \begin{pmatrix} 0 & 2 & 0 \\ 1 & 1 & 1 \\ 0 & 4 & 0 \end{pmatrix}$$

(5)

$$\text{Im}(d_{A_t}) = \text{Span}(\text{colonne di } A)$$

$$= \text{Span}\left(\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 4 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}\right) = \text{Span}\left(\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 4 \end{pmatrix}\right)$$

$$\text{Ker}(d_{A_t}) \Leftrightarrow A_t \cdot \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{cases} 2x_2 = 0 \\ x_1 + x_2 + x_3 = 0 \\ 4x_2 = 0 \end{cases} \Leftrightarrow \begin{cases} x_2 = 0 \\ x_1 = -x_3 \end{cases}$$

$$\Leftrightarrow \left\{ t \cdot \begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix} \right\}$$

$$\underbrace{\begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 1 \\ 4 \end{pmatrix}}_{\text{Im}} , \underbrace{\begin{pmatrix} -1 \\ 0 \\ 1 \end{pmatrix}}_{\text{Ker}}$$

sono lin. IND.



$$\mathbb{R}^3 = \text{Im}(d_A) \oplus \text{Ker}(d_A)$$

(3) $f: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ t.c.

(6)

$$\text{Im}(f) = \left\langle \begin{pmatrix} 1 \\ 4 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -3 \\ 1 \end{pmatrix} \right\rangle$$

$$\text{Ker}(f) = \left\langle \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle$$

$\dim(\text{Im}) = 2$, $\dim(\text{Ker}) = 1 \Rightarrow$ una tale
epp. esiste

$\text{Im}(f) = \text{Spem}(\text{colonne di } A)$

PROVIAMO con $A = \begin{pmatrix} 1 & 1 & a \\ 4 & -3 & b \\ 1 & 1 & c \end{pmatrix}$

condizione $\text{Ker} = \left\langle \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\rangle \Leftrightarrow A \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

$$\Leftrightarrow \begin{pmatrix} 1 & 1 & a \\ 4 & -3 & b \\ 1 & 1 & c \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\Leftrightarrow \begin{cases} 1 + 1 + a = 0 \\ 4 - 3 + b = 0 \\ 1 + 1 + c = 0 \end{cases} \Leftrightarrow \begin{cases} a = -2 \\ b = -1 \\ c = -2 \end{cases}$$

una possibile matrice A è

$$A = \begin{pmatrix} 1 & 1 & -2 \\ 4 & -3 & -1 \\ 1 & 1 & -2 \end{pmatrix}$$

Sol.

④

$$A = \begin{pmatrix} 6 & 0 & -4 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 2 & 0 \\ 2 & 0 & 0 & 4 \end{pmatrix}$$

⑦

$$i) P_A(\lambda) = \det(A - \lambda \text{Id}) = -\lambda \cdot (4-\lambda) \cdot \det \begin{pmatrix} 6-\lambda & -4 \\ 1 & 2-\lambda \end{pmatrix}$$

$$= -\lambda(4-\lambda)(\lambda^2 - 8\lambda + 16) = -\lambda \cdot (4-\lambda) \cdot (4-\lambda)^2 = -\lambda \cdot (4-\lambda)^3$$

\Rightarrow radici: 0, 4

autovettori

$$0 \quad \text{m.o.}(0) = 1$$

$$4 \quad \text{m.o.}(4) = 3$$

• m.g.(0) = 1 poiché $1 \leq \text{m.g.} \leq \text{m.o.}$

$$\text{m.g.}(4) = \dim(\text{Ker}(A - 4\text{Id}))$$

$$A - 4\text{Id} = \begin{pmatrix} 2 & 0 & -4 & 0 \\ 0 & -4 & 0 & 0 \\ 1 & 0 & -2 & 0 \\ 2 & 0 & 0 & 0 \end{pmatrix} \quad , \quad \text{rk} = 3 \quad \Rightarrow \quad \text{m.g.}(4) = 1$$

$$ii) \quad V_0 = \left\langle \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix} \right\rangle \quad ; \quad V_4 = \left\langle \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} \right\rangle$$

iii) A è triangolare

A non è diagonale poiché $\text{m.g.}(4) = 1 \neq 3 = \text{m.o.}(4)$